A HYBRID METHOD TO DESIGN AND OPTIMIZE A BATTERY CLOSED-LOOP SUPPLY CHAIN: MULTI-OBJECTIVE APPROACH

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A thesis presented to Ryerson University

in partial fulfillment of the requirement for the degree of Master of Applied Science in the program of Mechanical and Industrial Engineering

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ABSTRACT

A HYBRID METHOD TO DESIGN AND OPTIMIZE A BATTERY CLOSED-LOOP SUPPLY CHAIN: MULTI-OBJECTIVE APPROACH

Master of Applied Science, 2017 Babak Mohamadpour Tosarkani Mechanical and Industrial Engineering Ryerson University

There are a variety of prominent factors associated with total expected profit of a closed-loop supply chain (CLSC). In a forward flow, volatility in transportation cost, inventory cost, and forecasting the market's demand are the most challenging issues for decision makers, while determining the rate of returned products and efficiency in recycling the returned products are crucial parameters to predict in reverse flow. In this thesis, it is aimed to develop and apply mixed-integer linear programming (MILP), scenario-based analysis, and fully fuzzy programming (FFP) methods to maximize the profit for a multi-echelon, multi-components, multi-product, multi-period battery CLSC in Vancouver, Canada. Furthermore, the proposed model is extended to multi-objective to consider the green factors related to plants and battery recovery centers. Fuzzy analytic network process (Fuzzy ANP) is utilized to convert the qualitative factors to the measurable parameters. Then, distance technique and &-constraint method are utilized for solving the multi-objective problem.

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LIST OF ACRONYMS

Analytic Network Process (ANP) Analytic Hierarchy Process (AHP) Closed-Loop Supply Chain (CLSC) Closed-Loop Supply Chain Management (CLSCM) Environmental Protection Agency (EPA) Fully Fuzzy Programming (FFP) Green Closed-Loop Supply Chain Management (GCLSC) Green Supply Chain Management (GSCM) High Temperature Metal Reclamation (HTMR) International Standards Organization (ISO) Mixed-Integer Linear Programming (MILP) Mixed-Integer Non-Linear Programming (MINLP) Multi-Objective Linear Programming (MOLP) Net Present Value (NPV) Multi-Criteria Decision Making (MCDM) Possibilistic Linear Programming (PLP) Quality Function Development (QFD) Returns On Investment (ROI), Return On Asset (ROA) Reverse Supply Chain (RSC) Supply Chain Management (SCM) Sealed Lead Acid (SLA). Triangular Fuzzy Numbers (TFNs)

CHAPTER 1

1.1. Introduction

Nowadays, companies are more enthusiastic about considering a variety of strategies related to supply chain management (SCM). Supply chain is a multi-echelon network creating relationships between multiple businesses (Lambert et al., 1998). In the competitive global market, competition occurs among supply chains. For such reasons, companies are supposed to manage their relationships with others existing in the same supply chain. Furthermore, potential benefits of SCM such as improvement in returns on investment (ROI), and return on asset (ROA) are other logical reasons to consider SCM by organizations. Therefore, improvement of SCM leads to more probable profits for all entities taking part in supply chain. These are a great number of advantages (including lower inventory level, reduction of demand's uncertainties, shorter lead time) stem from development of SCM.

1.2. Business definition of SCM

As indicated by Fig.1.1, SCM can be defined as the planning, managing, executing and analysing of all activities comprising of procurement, production, research and development, customer service, marketing, sale, purchasing, and logistic through the collaboration of suppliers, producers, intermediaries, and customers with the view of creating value.

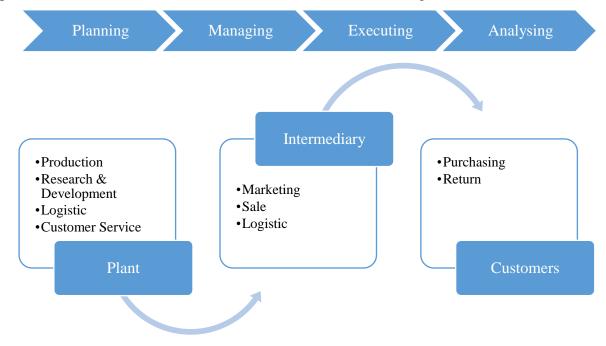


Fig.1.1. Flow of products and services in supply chain

1.2.1. Scope of supply chain

The scope of supply chain can be identified in terms of the number of firms, products, and activities involving in supply chain. SCM is defined as the integration of all efforts associated with fulfilling the market's demand through the transferring goods and services from the first stage to the end user. Such efforts may include management, procurement, production, inventory management, order processing, transportation, and customer service (Cooke, 1997). SCM may also entail collaborative activities between chain members such as operation management, research and development, product design, and marketing research (Mentzer, 1993).

1.2.2. Objectives of SCM

The objectives of SCM can be defined as the efficient usage of resources to satisfy customer's demand, matching product's specification with customer's expectation, reducing the holding inventory and work-in-process (WIP) with the aim of building competitive advantage for supply chain (Cooper, 1993; Cavinato, 1991; Houlihan, 1985).

1.2.3. Distinguishing SCM from logistic management

Logistic typically refers to the activities occurring under the supervision of a single organization such as production planning and transportation, while supply chains refer to the coordination of companies collaborating with each other to deliver a product to customers such as planning, implementing, and controlling of the networks.

1.2.4. The reverse supply chain (RSC)

The RSC (including activities related to collection and recovery of returned products) has emerged as a necessary part of business on account of environmental issues and economic aspects. Under the British Columbia recycling regulation (environmental management act), producers are not allowed to sell battery in province unless they take part in a stewardship plan consisting of free collection and recycling of used batteries. Remanufacturing of returned product makes impact on saving natural resources, and reduces the environmental issues.

1.2.5. Implication of closed-loop supply chain (CLSC)

The CLSC has been emerged to consider returned products for the purpose of recovering added value by remanufacturing or recycling the whole products or some of their subassemblies. The business definition of CLSC is to make the best use of value creation over the entire life cycle of a product with dynamics recovery of value from different types and volumes of return over time during the design, control, and operation of a system (Guide et al., 2003). As shown by Fig.1.2, the CLSC is comprised of forward and reverse flows. Forward flow consists of all actions that result in the transformation of raw materials to finished products. In the forward supply chain, facilities receive raw materials from suppliers, and manufacture the products to send to retailers. Thereafter, retailers are responsible to fulfill market's demand and hold some of the products as the inventory for the next periods. Activities of the collection and recovery of the returned product in supply chain management (SCM) are classified under the RSC. Therefore, the integration of the forward and reverse flows in supply chain creates the CLSC.



Fig.1.2. Closed-loop Supply Chain (CLSC)

There is a significant profit associated with CLSC due to the value recovery of the returned product. In SCM, economic aspects have been considered as a single objective, while in closed-loop supply chain management (CLSCM) both economic and environmental aspects are emphasized.

Customers may return products to the supply chain in account of different reasons including commercial return, end of use return, end of life return, repair and warranty return over the product life cycle. Therefore, CLSC should comprise of all activities related to product recovery consisting of returned product acquisition, product disassembly, remanufacturing and remarketing. In this sense, market's demand for remanufactured product, cost of remanufacturing and accessibility to returned product are three elements influencing the profitability of CLSC.

In this thesis, it is intended to design a battery CLSC in Vancouver, Canada. In this field, there is a stewardship organization named Call2Recycle Canada, Inc. committed to collect and recycle used batteries at no cost for consumers. Based on their official announcement published in call2recycle.ca, more than 4.5 million kg of batteries were collected in 2012. They aim to bring together battery and electronics industries, businesses, consumers, government agencies, non-profit organizations, and retailers for the purpose of minimizing the environmental impacts of batteries at the end of their lives.

1.3. Battery recycling

Call2Recycle has been recognised as the premier product stewardship organization in North America. According to their vision, protecting the environment is their main objective by managing the product life cycle and setting environmental standards for processing and material management. Call2Recycle hires independent third-party auditors to assure that process of collecting material through its program comply with assigned standards. Call2Recycle does not believe that just collecting battery is good enough, besides it is important to optimise the recycled portion of used battery in making a new product.

The most elements of batteries depending on type of battery (including Carbon, Iron, Lithium, Manganese, Sulphur, Zinc) can be used in making new batteries and the remainder, which is less than1 percent, can become slag as the input for roads construction.

1.3.1. Importance of battery recycling

There is a great deal of concern associated with battery recycling on account of incremental demand by households, and industries as their power resources. Hence, it is supposed to have a comprehensive plan to collect used batteries; otherwise left batteries in environment may harm humans and habitat due to comprising of toxic materials. Although there is no threat to human

health associated with battery's usage, it will become dangerous when it is discarded improperly or ended up in landfills due to spreading out its chemical material into soil and groundwater.

1.3.2. The different types of batteries and related recycling method

Batteries are mostly categorized as the electrochemical devices made of Anode, Cathode, Electrolyte, Separator, and Case. Characteristic of each type of battery can be defined as the utilization of materials for electrolyte, electrodes, etc. For instance, separator and external cases are usually made of polymeric materials and steels, while the other parts such as electrodes and electrolytes are varied in different types of batteries.

Batteries are divided in two main categories of disposable and rechargeable in different common sizes of AAA, AA, C, D, 9V, coin cell, button cell, and sealed lead acid (SLA). Alkaline, Lithium, Silver-oxide, Zinc-carbon are the main types of disposable batteries, while Lead-acid, Lithium ion, Nickel-metal hybrid (NiMH), Nickel-zinc (NiZn) are categorized as the rechargeable batteries.

1.3.3. Alkaline battery

Alkaline batteries are obtained their names due to the usage of potassium hydroxide (Alkaline) as the electrolyte along with zinc powder as the anode, and manganese dioxide as the cathode. The Alkaline batteries provide almost 4 to 5 times more energy compared to zinc-chloride batteries with the same size. The typical voltage of Alkaline battery is 1.5 V. This type of battery is the most common type designed for different appliances in various cylindrical shapes.

Alkaline batteries in different sizes of AAA, AA, C, D, 9V can be 100 percent recycled and reused in new products. The returned alkaline batteries are separated into different components of zinc, manganese, potassium, steel, nickel, and plastic. The first three components of zinc, manganese and potassium are utilized as a premium micro-nutrient to grow corn. Furthermore, 100 percent of the nickel and steel used in returned alkaline batteries can be recycled (RMC Technology).

1.3.4. Zinc-carbon battery

This type of battery comprises of a carbon rod as the cathode in a mixture of manganese dioxide and carbon powder packed in a zinc container as the anode. This type of battery is durable with voltage value of 1.5 V. Since zinc-carbon battery has cheaper price than the other common types of batteries in the market, electronic appliances are lunched to the market with these batteries.

The zinc-carbon batteries can be also recycled the same as Alkaline batteries or by utilizing high temperature metal reclamation (HTMR) method.

1.3.5. Lead-acid battery

Lead-acid batteries are used in automobiles for the purpose of fulfilling the high current needing for the heavy motors. The other form of such battery known as wet cell battery has been applied for backup power supply and portable emergency light.

As illustrated by Fig.1.3, 99 percent of vehicle batteries can be recycled and reused for the purpose of making new lead-acid batteries and other products such as cleaners. In this way returned lead-acid batteries are disassembled to lead, plastic, and battery acid. The lead and heavy materials are gathered and shaped to lead ingots which are then melted down to produce lead plates using for new battery. Similarly, plastic cases can be remanufactured for new battery, while the returned battery acid is converted to sodium sulphate using in detergent.

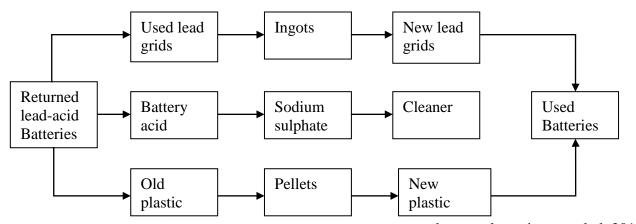


Fig.1.3. The recycling method of lead acid battery adopted from (how are batteries recycled, 2017).

1.3.6. Mercury battery

Mercury battery is a type of non-rechargeable battery including mercuric oxide and zinc oxide in an alkaline electrolyte. Such type of battery is less popular due to low output of voltage and usage of mercury which is toxic and harmful for humans. Mercury battery was produced in a shape of button cell for cameras, calculators, and watches. The metal used in such type of battery can be recovered by controlled-temperature process. Since the passage of Mercury-Containing and Rechargeable Battery Management Act in 1996, production of batteries using mercuric oxide has been decreased.

1.3.7. Lithium battery

Lithium batteries are in the category of batteries with capability of producing voltages in the range of 1.5 to 3.2 V. Therefore, the voltage production of such type of battery can be almost two times more than zinc-carbon and alkaline batteries. They comprise metallic lithium as the anode and cathode. Although lithium batteries are more expensive, they can be used in place of alkaline battery in various appliances such as clocks, and cameras due to the longer life.

The lithium batteries are disassembled by using shredder. The contents are submerged in caustic water; thereafter metals are separated from caustic solution, and sent to recyclers. Continuously, lithium can be recycled from filter solution which may be used to produce lithium ingot.

1.3.8. Lithium ion batteries

Lithium ion battery is one of the most popular types of rechargeable battery for portable electronics. They are generally lighter than other types of rechargeable batteries. The electrode of lithium ion battery includes the lightweight lithium and carbon compared to the metallic lithium utilizing in non-rechargeable lithium battery. The metal used in this type of battery can be recycled 100 percent through HTMR method.

1.3.9. Silver oxide batteries

This type of battery includes zinc as the anode and silver oxide as the cathode with alkaline electrolyte (either potassium hydroxide (KOH) or sodium hydroxide (NaOH)). Although silver

oxide batteries are more expensive than alkaline batteries, they are more durable and have been designed for watches and calculators in small sizes, and for military applications in larger sizes.

1.4. Market's real locations

In this thesis, it is aimed to assume real locations for potential plant(s), retailer(s), markets, and collection center(s) with the aim of estimating real distances affecting the transportation cost. According to the official website of Vancouver, areas of the city are divided to 22 wards which are indicated in Table 1.1 (Areas of the city, 2017). Furthermore, the population of each ward can be applied for estimating the market's demand.

vancouver wards along w	ini men related population			
1. Downtown	54,690	12. Shaughnessy	8,810	
2. West End	44,540	13. South Cambie	7,680	
3. Strathcona	12,165	14. Riley Park	21,795	
4. Grandview- Woodland	27,305	15. Kensington-Cedar Cottage	47,470	
5. Hastings- Sunrise	33,990	16. Renfrew- Collingwood	50,500	
6. Mount Pleasant	26,400	17. Kerrisdale	14,735	
7. Fairview	31,440	18. Oakridge	12,440	
8. Kitsilano	41,375	19. Marpole	23,835	
9. West Point Grey	12,795	20. Sunset	36,290	
10. Dunbar	21,745	21. Victoria-Fraserview	30,710	
11. Arbutus-Ridge	15,910	22. Killarney	28,455	

Table 1.1.

Vancouver wards along with their related population based on census 2011

1.5. Unit price transportation cost

As illustrated by Fig.1.4, there is a significant difference between average retail price for gasoline in Vancouver and other area in Canada. The average price of gasoline in Canada was 119.03 cents per litre between January 2016 to January 2017 with a minimum of 105.9 cents on February 2016, and a minimum of 128.3 cents per litre on October 2016. As indicated by Fig.1.4, there is a significant fluctuation in gasoline price during 2016. Therefore, it will not rational to assume a specific unit transportation cost per kilometre for our proposed model. In this sense, it is aimed to apply possibilistic programming method in order to have a realistic model.

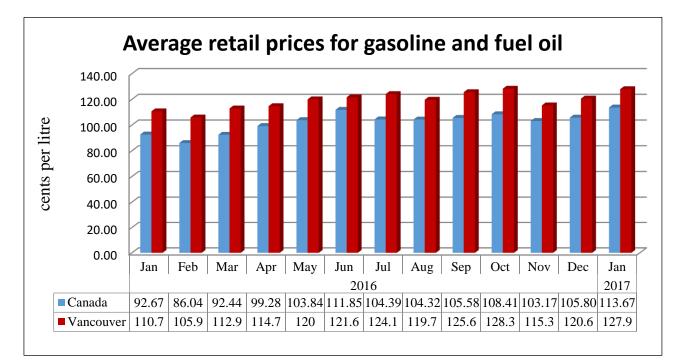


Fig.1.4. Comparison of fuel price between Vancouver in BC and other area in Canada. (Data is adopted from Statistics Canada, 2017)

1.6. Problem statement

Decision makers are supposed to deal with a variety of ambiguities associated with profitability of CLSC. Market's demand is the most important factor affecting both cost and profit of CLSC. If there is no volatility in demand, market's behaviour will comply with a specific trend. Then, decision makers are free to set up optimised policy for supply chain in aspect of inventory level. However, often there is too much imprecise information which does not allow decision makers to establish a stable method to deal with market's demand in real-life. Furthermore, some other factors also influence the policy implementing in CLSC in aspects of production and inventory levels such as back order cost, remanufacturing cost, and disposal cost. The other prominent factor is a collection rate of the returned products which has massive impact on profit of CLSC. However, collecting of returned batteries is irregular, and decision makers are not able to forecast the receiving of used batteries.

Unit transportation cost is one of the main elements of variable costs incurred in CLSC. It is mostly related to economic factors such as oil price and inflation rate. In addition, transportation cost is one of those factors which affects the relation between producers and retailers in aspect of meeting customers' demand.

Accordingly, it is tried to apply possibilistic approach to interpret the behaviour of the proposed CLSC under uncertainties in aspect of fluctuation in market's demand, returned product, and volatility of transportation cost.

In this thesis, it is aimed to answer the following questions:

- Which supplier(s) should be chosen?
- Which location(s) should be chosen for plant(s)?
- Which retailer(s) should be chosen?
- Which battery recovery center(s) should be assumed to collect the used batteries?
- How many components should be purchased from each supplier?
- How many products should be produced by plants, held by retailers, and sold to the markets in the proposed CLSC?

1.7. Aim and research contributions

In this thesis, a multi-objective CLSC model is introduced for battery recycling under uncertainty of demand, return, selling price, and the cost associated with purchasing raw materials, transportation, production, inventory, disposal (variable costs), opening plant, retailer, and battery recovery center (fixed costs). Hence, it is aimed to maximize the total profit as the 1st objective, and to consider green performance of plants and battery recovery centers as the 2nd objective. It is intended to apply real transportation cost to evaluate the effects of uncertainty and volatility in fuel price. For such reasons, fuel consumption rate obtained from the fuel consumption guide (Natural Resources Canada, 2014), and monthly average retail price of gasoline in Vancouver for 2016-2017 are considered. In author's view, this study is the first

examination that considers a battery CLSC network in Vancouver. Initially, a deterministic model is introduced for a battery CLSC. The proposed model is considered for a multi-echelon, multi-components, multi-products CLSC in multiple periods. Thereafter, scenario-based analysis is applied to evaluate the deterministic model under different scenarios of alteration in market's demand and returned products. In order to develop the model, fuzzy ANP is utilized to consider the green performance of plants and battery recovery centres.

To deal with uncertainty, FFP method is developed and utilized to calculate the triangular fuzzy profit, and green performance separately. Accordingly, it is tried to find the trade-off surface of solution for those objectives through the distance technique and \mathcal{E} -constraint method. The proposed methodology can be helpful to determine the best CLSC network under imprecise information.

The research contributions of this thesis are introduced as follows:

 Designing and examining CLSC network of battery in Vancouver with regard to the related organizations in Canada.

 Application of scenario-based analysis to develop the proposed model under the risk of unexpected changes in demand and return.

Employing Fuzzy ANP to convert the qualitative factors to the quantitative parameters.

• Application of fully fuzzy programming (FFP) method to evaluate the impacts of several sources of uncertainty on CLSC network simultaneously. Since, the configuration of battery CLSC may be applied for making strategic decision and it is impossible to change in a short-term, it is necessary to consider all possible optimal range of decision variables and objective function.

• Employing the combination of possibilistic (fuzzy) and scenario-based analysis to involve more one alternative for lower, middle, and upper range of demand and return.

• Utilization of distance technique and E-constraint method to determine the tradeoff surface of solution.

Assuming real distances in the proposed multi-echelon CLSC through Google
 Maps for estimating real transportation cost.

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1.8. Research methodology

In this section, some methods that are applied in this thesis are described.

1.8.1. Mixed-integer linear programming (MILP)

MILP is usually applied to optimize linear objective function with respect to linear constraints. In this approach, variables participating in objective function and constraints are categorized as non-negative variables, integer variables, and binary variables.

1.8.2. Multi-objective linear programming (MOLP)

MOLP can be applied in various fields of engineering, economics, and science when it is required to optimize more than one objective function simultaneously. However, the different objectives are not usually homogenous leading to difficulties for integration. Such type of programming will provide a set of solutions that are called Pareto optimal solutions instead of unique solution. Deb et al. (2008) categorized the process of multi-objective optimization into three phases; building the model, optimization, and making decision.

Here is the mathematical development of the mono-objective (1.1) to the multi-objective optimization (1.2). Instead of one objective function $f(\vec{x})$, there are multiple objectives in (1.2) which are shown by $\vec{f}(\vec{x})$.

$\text{Minimize } f(\vec{x}) (1.1)$	$\text{Minimize } \vec{f}(\vec{x}) \qquad (1.2)$
Subject to.	Subject to.
$\vec{g}(\vec{x}) \leq 0,$	$ec{g}(ec{x}) \leq 0,$
$\vec{h}(\vec{x}) = 0$	$\vec{h}(\vec{x}) = 0$
	$ec{k}(ec{x}) \leq 0,$

1.8.3. Fuzzy analytic network process (FANP)

FANP is a method of measurement based on experts' judgment under uncertainties. Preferences of human for making decision in many real situations is uncertain. Therefore, applying exact numerical values for comparison can be unfavourable. On the other hand, evaluation of factors may be influenced by characteristics of the decision makers (Nilashi et al., 2016). For such reasons, fuzzy methods can be applied in the process of making decision. In this thesis, FANP (which is the extension of ANP method in the case of fuzziness) is considered for ranking the potential plants and battery recover centers based on green performance.

1.8.4. Fully fuzzy programming (FFP)

There is often imprecise information in real life particularly in CLSC under uncertainties. Therefore, fuzzy numbers and variables should be applied in modeling CLSC. In this way, there are a variety of methods to deal with uncertainty as follows:

- Verdegay approach which can be applied for linear programming with fuzzy resources.
- Zimmermann approach which can be utilized for programming with fuzzy objective.
- Fuzzy integer programming which can be used for programming with fuzzy resources and objective.
- FFP method which can be employed for programming with fuzzy resources, objective, and decision variables.

In this thesis, it is intended to apply FFP method to interpret the proposed CLSC under uncertainty of demand, returned product, transportation cost, and other related cost to manufacturing process such as production cost, and holding inventory cost.

1.8.5. Scenario-based analysis

It is intended to employ the scenario-based analysis for finding a solution with respect to any probable circumstances of random parameters. Rosenhead et al. (1972) categorized the environment of decision making to certain, uncertain, and risky situations. In certain situation, all parameters are deterministic, while there is imprecise information in both risky and uncertain situations. In risky situation, uncertain parameters comply with probability distributions which are known by decision makers, but in uncertain situation parameters are unknown and there is not enough information about the probability distribution of them. Scenario-based analysis is applied for risky situation for the purpose of optimizing the expected value of the objective function. In this thesis, it is aimed to maximize profit with regard to any possible changes in market's demand, and returned product.

1.9. Organization of the thesis

Chapter I was commenced with the introduction of some basic information about background of CLSC, battery recycling and stewardship plan, market's location, problem statement, and thereafter research objectives and methodology were explained, respectively. Chapter II includes the review of related literatures. In Chapter III, a deterministic model is introduced for a battery CLSC network, and thereafter scenario-based analysis is utilized. In Chapter IV, the fuzzy ANP method is utilized to convert the qualitative factors to the quantitative parameters. In Chapter V, FFP algorithm is defined comprehensively and applied for the proposed battery CLSC network. To solve the proposed multi-objective model, each fuzzy problem is solved separately, and then distance method along with \mathcal{E} -constraint method are applied to address the multi-objective model. In Chapter VI, conclusions of this thesis along with future works are discussed.

CHAPTER 2. REVIEW OF LITERATURE

2.1. Introduction

In this chapter, several papers and methodologies related to RL and CLSC are reviewed. Since it is aimed to evaluate decision making in certain, uncertain, and risky situations in this thesis, MILP, stochastic (scenario-based analysis), and fuzzy programming are chosen as the main fields. Accordingly, related studies for designing the deterministic model are discussed in Section 2.2. Thereafter, review of some investigations including multi-objective models are classified in Section 2.3. Applications of stochastic programming (scenario-based analysis) in CLSC are discussed in Section 2.4. In addition, several studies associated with utilization of fuzzy programming are provided in Section 2.5.

2.2. Deterministic models applied in CLSC

There are a variety of studies associated with RL and CLSC configuration. Designing a deterministic model for facility locations has been applied in the most cases. Jayaraman et al. (1999) employed MILP to determine the location of remanufacturing and distribution centres along with optimal numbers of products to be produced, transported, and held as the inventory. Fleischmann et al. (2001) configured CLSC with regard to forward facility locations. They applied copier remanufacturing example to evaluate the accuracy of the proposed CLSC. Kim et al (2006) introduced mathematical model for a CLSC to maximize the profit. Ko and Evans (2007) utilized MILP model for a multi-product, multi-period, two-echelon network included forward and reverse flows at the same time. Wang and Hsu (2010a) examined the integration of forward and reverse flows for generalized CLSC by application of MILP. Achillas et al. (2010) used MILP to optimize RL network due to increase of waste in the electronic industry. Sasikumar et al. (2010) designed a multi-echelon RL network for a case study of truck tire. They employed MINLP to maximize the profit of the proposed model.

Fahimnia et al. (2013) developed an integrated mathematical model for environmental CLSC in which carbon emission was represented by dollar carbon cost. MILP was applied to formulate the proposed multi-product, multi-period CLSC for the purpose of minimizing the total cost of manufacturing, transportation, and carbon cost.

Cardoso et al. (2013) applied MILP for planning the supply chain combined by reverse logistic activities. They also utilized scenario tree method to deal with uncertainty of demand for

the purpose of maximization of expected net present value related to discounted cash flows. Oh and Jeong (2014) considered CLSC configuration in fashion industry on account of increasing usage of synthetic fiber leading to growth of CO₂ emission. They employed multi-objective MILP to find the optimal trade-off between CLSC profit and CO₂ emission. Hashemi et al. (2014) applied MILP to maximize the total profit of a CLSC in aerospace industry. Kalaitzidou et al. (2105) proposed a general mathematical model for multi-echelon, multi-product CLSC network. They applied multi-period MILP to minimize the operational cost.

Amin et al. (2017) examined a CLSC network concentrated on a tire remanufacturing. The reason why they considered such case was high incentive of tire remanufacturing due to profit and responsibility for protecting environment. They aimed to maximize the total profit of the proposed model comprised of multiple products, suppliers, plants, demand markets, and collection centers in multiple periods. They also applied decision-tree methodology to calculate net present value (NPV) of the problem in case of uncertainty in demand and returns of tires by customers based on a realistic network in Toronto, Canada. Özceylan et al. (In press) examined CLSC in automotive industry, since a great number of manufacturers are supposed to collect and recycle their end-of-life products. They employed deterministic linear programming to address their multi-echelon, multi-products, multi-period model. Similarly, Shimada and Wassenhove (In press) considered the effects of recycling law on CLSC in home appliances and computer industry in Japan.

Al-salem et al. (2016) employed an MINPL to minimize the total cost of forward and reverse supply chain. The non-linear objective function was linearized by performing the piecewise method. According to their findings, significant cost saving can be achieved as result of integration the forward and reverse flows which leads to CLSC. Kaya and Urek (2016) applied MINLP to maximize the profit in CLSC. They also developed heuristic for the solution of their proposed multi-echelon model. Kisomi et al. (2016) proposed an integrated model considering robust optimization theory in account of addressing uncertain environment related to supply chain configuration and supplier selection. They compared the obtained results with deterministic model, and utilized sensitivity analysis in order to validate their proposed multi-echelon, multi-product, and robust model.

2.3. Multi-objective models for CLSC

Nowadays, applications of multi-objective models seem inseparable with formulation of CLSC networks due to the importance of environmental issues. Sheu et al. (2005) presented a multi-objective model for green supply chain. Return ratio of used product and related governmental subsidies were considered to formulate RL. Das and Posinasetti (2015) presented mathematical model integrated with environmental concerns for multi-product CLSC. They aimed to maximize profit with regard to optimization of consumed energy and harmful emission. The multi-objective model was solved by goal programming.

Shakourloo et al. (2016) applied a multi-objective integer linear programming along with fuzzy analytic hierarchy process (AHP) to examine their proposed CLSC. They aimed to optimize the number of products providing by suppliers along with number of returned products required to be remanufactured. Ruimin et al. (2016) utilized a robust multi-objective MINLP to examine environmental CLSC under uncertainty of demand and cost parameters in the realistic network. They intended to minimize the total cost and environmental impacts of CLSC simultaneously in the proposed multi-objective model.

Talaei et al. (2016) utilized MILP to design a closed-loop green supply chain network with regard to environmental issues such as rate of carbon dioxide emission. In addition, they examined their proposed model under uncertainty of demand and variable cost by utilizing a robust fuzzy programming. Mohammed et al. (2017) proposed a multi-period, multi-product CLSC model with the aim of minimizing the total cost and carbon emission. Robust optimization approach was applied to address uncertainties. Chen et al. (2017) believed that reducing carbon dioxide emission should be prioritized in implementing the sustainable strategy in a CLSC. For such reasons, two objectives comprising total cost and reducing carbon emission were determined for the proposed multi-objective CLSC. A deterministic mixed-integer programming (MILP) was applied as the methodology for the proposed model. According to their findings enterprise should use an appropriate recycling strategy to reach an efficient economic situation in case of applying the carbon emission regulation. Xu et al. (2017) introduced a novel global reverse supply chain emphasizing the uncertainty of waste collection, carbon emission, and some issues existing in global supply chain such as exchange rate and transportation cost. Mixed integer-linear programming and robust optimization were applied to address a multi-echelon, multi-product, multi-period model.

2.4. Stochastic programming (scenario-based analysis) in CLSC

To design CLSCs, stochastic programming can be employed in optimization models to deal with imprecise information when probability of each scenario is known. Hu and Bidanda (2009) utilized stochastic dynamic programming to design a network based on product life cycle. They aimed to determine the optimal strategy to maximize the total profit of the proposed model.

Paksoy et al. (2011) proposed an optimization model to examine the efficiency and environmental practices in a multi-product CLSC. Stochastic programming was utilized to investigate the trade-off solution in a proposed realistic network. Amin and Zhang (2013) introduced three-stage model for CLSC. In the first step, quality function development (QFD) was applied to evaluate suppliers and remanufacturing centers. Furthermore, fuzzy sets theory was utilized to deal with uncertainty in the process of decision making. In the second step, stochastic mixed-integer non-linear programming was employed to design the CLSC network with regard to uncertain demand. In the third step, multi-objective MILP was used to identify the trade-off solutions between the total cost, importance of facilities (suppliers, refurbishing, and remanufacturing centers), defect rate, and on-time delivery.

Litvinchev et al. (2014) discussed about designing an RL network including locations of distribution and inspection centers along with remanufacturing facilities. They employed stochastic programming to formulate a multi-product CLSC with respect to scenario-base demand. Zeballos et al. (2014) utilized stochastic programming for a multi-period, multi-product CLSC. Multiple scenarios were assumed to consider the effects of uncertain demand and raw material supplies. In the proposed model, a scenario tree approach was applied to indicate all possible discrete events. Each node of scenario tree represented a possible outcome estimated by given probability. Francie et al. (2015) employed stochastic programming for a printer cartridge CLSC. They aimed to minimize the total cost incurred by occurrence of waiting customers and holding inventories related to the finished and returned products. Vahdani and mohammadi (2015) introduced a bi-objective optimization model for the purpose of minimizing the total cost and waiting time in the queue. They applied a hybrid solution method according to stochastic programming and robust optimization to deal with uncertainty in the model.

Soleimani et al. (2016) believed that an integrated approach is necessary for designing and planning decision levels to achieve the best performance of CLSC. They also said that real markets can be unpredictable in the case of demands and products' price. An MILP was applied

for a multi-product, multi-period CLSC in order to deal with stochastic demand and products' price. Dutta et al. (2016) introduced a recovery model for a multi-period CLSC with the aim of improving rate of returned products by utilizing the buy-back offer. They applied chance constrained programming to convert the probabilistic demand constraints to the deterministic equivalents. Zhalechian et al. (2016) designed a sustainable CLSC with regard to economic, environmental, and social aspects. They considered CO₂ emission, fuel consumption, and wasted energy as the environmental issues, creating job opportunities as the social aspects, and economic growth rate. The stochastic-possibilistic programming was applied to address uncertainty of the proposed CLSC. Keyvanshokooh et al. (2016) proposed a profit optimization model for CLSC network by considering the economic, environmental, and social concerns. They developed a hybrid robust-stochastic programming method to deal with two different types of uncertainties comprised of stochastic scenarios for transportation costs along with multi-level uncertainty of demand and return.

Feitó-Cespón et al. (2017) employed a stochastic programming along with a multi-criteria programming for the purpose of considering various objectives to deal with uncertainty in a sustainable supply chain network. They also proposed a performance indicator with the aim of evaluating the obtained solution and reducing the effects of uncertainty on decision making. Jeihoonian et al. (2017) applied a two-stage stochastic mixed-integer programming to address uncertainty of returned products quality in CLSC. A scenario reduction method was utilized to cope with several scenarios existing in their proposed model. Thereafter, they used L-shaped algorithm and Pareto-optimal cut to solve the reduced stochastic problem.

2.5. Fuzzy programming in CLSC

There are several studies that have considered fuzzy programming to deal with uncertainties. In this sense, different fuzzy methods (e.g., Verdegay approach, Zimmermann approach, fuzzy goal programming, fuzzy intervals, and fuzzy integer programming) have been employed. In the case of nondeterministic approaches, some parameters are assumed to be uncertain. As illustrated in Fig.2.1, demand and return have been assumed as uncertain parameters in the most studies due to the significant contributions to the profit of CLSCs. Furthermore, some other uncertain parameters are lead time (Lieckens and Vandaele, 2007), environmental issues (Wang and Hsu, 2010b), delivery time (Pishvaee and Torabi, 2010), and risk factor (Lundin, 2012).

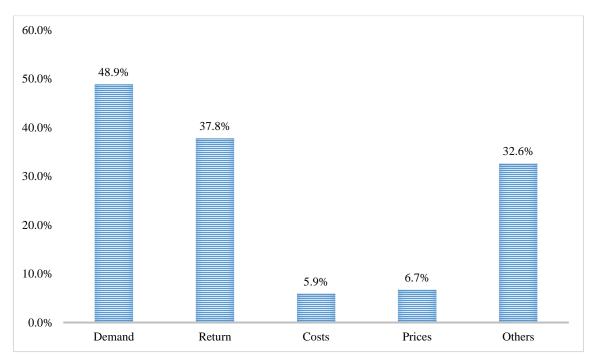


Fig.2.1. Uncertain parameters adopted from (Govindan et al., 2015)

Zarandi et al. (2011) designed a network distribution for a CLSC. They solved the proposed model by a fuzzy goal programming method. Pishvaee and Razmi (2012) offered a multi-objective fuzzy model for an environmental supply chain. They applied an interactive fuzzy approach to minimize the total cost of supply chain and environmental issues. Costantino et al. (2012) utilized a fuzzy programming approach to examine the sustainable CLSC. They aimed to minimize the total cost, consumption rate of energy, and CO₂ emission in the case of desktop computer supply chain. Vahdani et al. (2013) offered optimization model for a multi-echelon, multi-product CLSC in the iron and steel industry. They applied fuzzy programming to solve the mathematical model.

Ramezani et al. (2014) designed a multi-product, multi-period CLSC. They proposed a fuzzy multi-objective model to maximize the profit and the quality along with optimization of delivery time. In the proposed fuzzy model, all coefficients were assumed to be fuzzy due to the uncertain environment. They employed fuzzy optimization approach to convert the fuzzy multi-objective model to the equivalent crisp version.

Jindal and Sangwan (2014) employed fuzzy MILP for a multi-facility, multi-product CLSC in a single period. They aimed to maximize the proposed model under uncertainty of demand along

with all types of possible costs related to CLSC. Alimoradi et al. (2014) developed a fuzzy MILP model to deal with uncertain returned products for a single-period, multi-product CLSC. Fallah-Tafti et al. (2014) designed a multi-period CLSC network with regard to uncertain costs and demand. A novel interactive fuzzy programming was employed to find the trade-off solution for the proposed multi-objective model (including minimization of the total cost and the delivery time along with maximization of suppliers' ranks).

Mirakhorli (2014) discussed about designing a CLSC which may have impacts on the performance of a logistic network. He applied an interactive fuzzy programming to address the fuzzy multi-objective optimization model. It was aimed to find an efficient solution for the objective functions comprised of total cost and delivery time with regard to uncertain demand and return.

Subulan et al. (2015) applied an interactive fuzzy goal programming method to solve the fuzzy multi-objective, multi-echelon, multi-period network for a tire CLSC. They expressed that recycling and remanufacturing should be taken more seriously on account of growing the environmental issues of used products. They believed that designing the efficient CLSC through the application of fitting disposal method along with appropriate collection and storage can diminish the environmental impacts of used products. Dai and Zheng (2015) designed a multiechelon, multi-product CLSC under uncertain demand and disposal rate. They applied stochastic and fuzzy programming to maximize the total profit of the model. Mohajeri and Fallah (2016) considered the recycling of product's end-of-life in a notebook CLSC. In the proposed model, it was aimed to minimize the total cost along with CO_2 emission during distribution, delivery, and recycling of the products. A fuzzy programming was applied to deal with uncertain parameters (recovery rate, landfilling rate, and demand) in a realistic CLSC network. Pham and Yenradee (2017) described that the supply chain performance is definitely affected by the design of its network. They claimed that considering facility location to design the supply chain may make the model more complicated. For such reasons, they introduced an alternative approach to design the supply chain network through a multi-echelon, multi-product manufacturing process. In addition, uncertain factors were taken into account by applying fuzzy theory. According to their findings, the fuzzy model was more reliable compared to the deterministic approach in case of cost effectiveness.

Authors	Uncertainty	Multi- product	Type of products	Multi- period	Multi- objective	Mathematical programming approach	Real locations
Cardoso et al. (2013)	Demand	\checkmark	-	\checkmark	-	MILP, decision tree	-
Fahimnia et al. (2013)	-	\checkmark	-	\checkmark	\checkmark	MILP	-
Hashemi et al. (2014)	-	~	Aerospace industry	\checkmark	-	MILP	-
Kalaitzidou et al. (2105)	-	✓	-	✓	-	MILP	-
Özceylan et al. (In press)	-	\checkmark	Automotive industry	\checkmark	-	MILP	✓
Amin et al. (2017)	Demand, return	\checkmark	Tire	\checkmark	-	MILP, decision tree	\checkmark
Chen et al. (2017)	-	-	Solar energy		\checkmark	MILP	-
Shakourloo et al. (2016)		\checkmark	-	-	\checkmark	multi-objective integer linear programming	-
Amin and Zhang (2013)	Demand	\checkmark	-	-	\checkmark	MILP, QFD, Stochastic programming	-
Zeballos et al. (2014)	Demand, raw material supplies	\checkmark	-	\checkmark		Stochastic programming	-
Vahdani and Mohammadi (2015)	Cost, capacity	\checkmark	_	-	✓	Stochastic programming, Robust optimization	-
Soleimani et al. (2016)	Demand, product's price	\checkmark	-	\checkmark	-	Stochastic programming	-
Dutta et al. (2016)	Demand	\checkmark	-	~	-	Stochastic programming	-
Jeihoonian et al. (2017)	Stochastic variable (quality of returned products)	\checkmark	-	-	-	Stochastic programming	-
Feitó-Cespón et al. (2017)	Stochastic variable (demand and waste generation)	\checkmark	-	_	-	Stochastic programming	-
Ruimin et al. (2016)	Demand, cost parameters	\checkmark	-	-	\checkmark	Robust multi- objective MINLP	~
Talaei et al. (2016)	Demand, variable cost	~	-	-	✓	Robust optimization	-
Kisomi et al.	Demand,	\checkmark	-	-	-	Robust	-

Table 2.1. Review of some mathematical programming approaches utilized in CLSCs modeling

Authors	Uncertainty	Multi- product	Type of products	Multi- period	Multi- objective	Mathematical programming approach	Real locations
(2016)	transportation cost					optimization	
Xu et al. (2017)	Waste collection level	\checkmark	-	\checkmark		Robust optimization	-
Mohammed et al. (2017)	Demand, return, carbon emission	\checkmark	-	\checkmark	\checkmark	Robust optimization	\checkmark
Fallah-Tafti et al. (2014)	Costs and demand	\checkmark	-	\checkmark	\checkmark	Fuzzy programming	-
Mirakhorli (2014)	Demand, return	-	-	-	\checkmark	Interactive fuzzy programming	-
Ramezani et al. (2014)	All parameters	\checkmark	-	\checkmark	\checkmark	Fuzzy optimization approach	-
Jindal and Sangwan (2014)	Demand, variable cost	\checkmark	-	-	-	Fuzzy programming	-
Mohajeri and Fallah (2016)	Recovery rate, landfilling rate, demand	-	Notebook (laptop) industry	-	-	Fuzzy programming	✓
Subulan et al. (2015)	-	~	Tire	~	\checkmark	MILP, Interactive fuzzy goal programming	~
Pham and Yenradee (2017)	Demand, cost of opening location- production, setup cost	\checkmark	_	\checkmark	-	Fuzzy programming	-
Proposed model	All parameters and decision variables	~	Battery	✓	✓	MILP, scenario- based analysis, fully fuzzy programming, fuzzy ANP	\checkmark

CHAPTER 3. APPLICATION OF MILP AND SCENARIO-BASED ANALYSIS TO DESIGN A BATTERY CLSC

3.1. Introduction

In this chapter, it is intended to introduce a deterministic model for a battery CLSC. The proposed model is considered for a multi-echelon (multiple suppliers, plants, retailers, markets, battery recovery centers, and disposal center), multi-component, multi-product CLSC in multiple periods. It is aimed to figure out which plant(s), retailer(s), and battery recovery center(s) should be chosen, how many components should be purchased, and how many products should be produced and sent to the market or kept as inventory to maximize the profit of the battery CLSC. The introduced model is evaluated under different scenarios based on market's demand and returned products through the application of scenario-based analysis.

The structure of this chapter is arranged as follows: Initially, the proposed battery CLSC network is explained comprehensively in Section 3.2. Subsequently, a related mathematical model is provided in Section 3.3. Therefore, some associated assumptions regarding the number of demand markets, quantity of demands and returned products along with the solutions are provided in Section 3.4. The definition and application of scenario-based analysis are provided in Section 3.5. Finally, summary of this chapter is discussed in Section 3.6.

3.2. Network description

As illustrated in Fig.3.1, it is assumed a multi-echelon CLSC model with multi-components, and multi-products in multiple-periods. The proposed CLSC is comprised of suppliers, plants, retailers, markets in the forward flow, and reverse flow includes battery recovery centers and disposal center. The structure of the CLSC integrates both forward and reverse flows. The plants purchase the main components of battery (including Anode, Cathode, Electrolyte, Separator, and Case) from suppliers, and produce three different types of batteries, and then such products are shipped to the retailers. Furthermore, retailers are willing to meet market's demand by keeping cumulative inventory as least as possible to reduce the holding inventory cost.

Thereafter, customers purchase the batteries. Some of the batteries are returned to the battery recovery centers. The returned batteries are decomposed to the main components. Some of the main components can be recycled and returned to the plants, while other unrecoverable parts are sent to the disposal center.

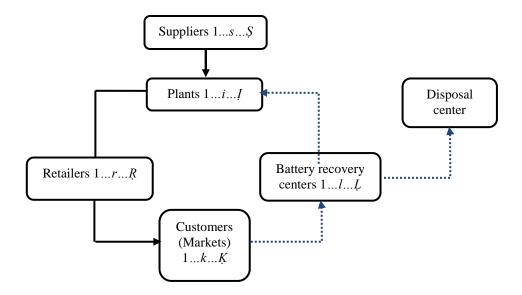


Fig.3.1. The proposed battery CLSC

3.3. Mathematical model

A deterministic mixed-integer linear programming model is employed to optimise the proposed network. Following sets, parameters, and decision variables are utilized:

Sets

 $J = \text{set related to products } (1 \dots j \dots J)$ $N = \text{set related to components } (1 \dots \eta \dots N)$ $S = \text{set related to suppliers } (1 \dots s \dots S)$ $I = \text{set related to possible plant sites } (1 \dots i \dots I)$ $R = \text{set related to possible retailer sites } (1 \dots r \dots R)$ $K = \text{set related to customers (market) sites } (1 \dots k \dots K)$ $I = \text{set related to locations of battery recovery centers } (1 \dots I \dots L)$ $T = \text{set related to periods } (1 \dots t \dots T)$ **Parameters** $\delta_j = \text{selling price of product } j$ $A_s = \text{fixed-cost associated with supplier } s$

- B_i = fixed-cost associated with opening plant i
- R_r = fixed-cost associated with opening retailer r
- C_l = fixed-cost associated with opening the recovery centers l

 $N_{s\eta}$ = purchasing cost of components η from supplier *s*

 $P_j = \text{cost of production related to product } j$

 F_{η} = unit cost of transportation related to components η from suppliers to plants

 E_{si} = the distance between locations *s* and *i*

 E_l = the distance between recovery centers l and disposal center

 G_j = unit cost of transportation related to product *j* from plants to retailers

 H_j = unit cost of transportation related to product *j* from retailers to markets

 M_j = unit cost of transportation related to product *j* from markets to battery recovery centers

 O_{η} = unit cost of transportation related to components η from battery recovery centers to plants

 θ_{η} = unit cost of transportation related to components η from battery recovery centers to disposal center

 $a_{\eta} = \text{cost saving of components } \eta$ due to product recovery

 f_{η} = disposal cost of components η

 d_{kjt} = demand of customer (market) k for product j related to period t

 ε_{η} = disposal fraction of the components η

 z_{kjt} = returned product *j* related to customer (market) *k* in period *t*

 $g_{i\eta}$ = number of capacity of plant *i* for components η

 h_{rj} = number of capacity of retailer *r* for product *j*

 n_{lj} = number of capacity of battery recovery center l for product j

 $u_{s\eta}$ = number of capacity of supplier *s* for components η

 v_{in} = number of components η in product j

 α_j = holding cost for product *j*

Decision Variables

 $Q_{si\eta t}$ = number of components η shipped to plant *i* by supplier *s* related to period *t*

 R_{irjt} = number of product j manufactured by plant i for retailer r related to period t

 S_{rkjt} = number of product j sold by retailer r to customer k related to period t

 T_{kljt} = number of returned product *j* from customer *k* to battery recovery centers *l* related to period *t*

 $U_{li\eta t}$ = number of components η shipped to plant *i* from battery recovery centers *l* related to period *t*

 $\lambda_{l\eta t}$ = number of components η shipped to disposal center from battery recovery centers l related to period t

 I_{rjt} = number of product *j* holding as the inventory in retailer *r* related to period *t*

 $V_i = 1$, if a plant of the manufacturer is located and set up at potential site *i*, 0, otherwise.

 $W_r = 1$, if the retailer located in site r is utilized to sell the products, 0, otherwise.

 $X_l = 1$, if the battery recovery centers located in site *l* is utilized to remanufacture the used products, 0, otherwise.

 $Y_s = 1$, if the supplier *s* is selected, 0, otherwise.

$$\begin{aligned} &Max \ z_{1} = \sum_{r} \sum_{k} \sum_{j} \sum_{t} (\delta_{j} - H_{j}E_{rk}) S_{rkjt} - (\sum_{s} \sum_{i} \sum_{\eta} \sum_{t} (N_{s\eta} + F_{\eta}E_{si}) Q_{si\eta t} + \sum_{i} \sum_{r} \sum_{j} \sum_{t} (P_{j} + G_{j}E_{ir}) R_{irjt} \\ &+ \sum_{r} \sum_{t} \sum_{j} \alpha_{j} I_{rtj} + \sum_{k} \sum_{l} \sum_{j} \sum_{t} M_{j}E_{kl}T_{kljt} + \sum_{l} \sum_{i} \sum_{\eta} \sum_{t} (-a_{\eta} + O_{\eta}E_{li}) U_{li\eta t} + \sum_{l} \sum_{\eta} \sum_{t} (f_{\eta} + \theta_{\eta}E_{l}) \lambda_{l\eta t} \\ &+ \sum_{s} A_{s}Y_{s} + \sum_{i} B_{i}V_{i} + \sum_{r} R_{r}W_{r} + \sum_{l} C_{l}X_{l}) \end{aligned}$$

s.t.

$$I_{rjt} = I_{rjt-1} + \sum_{i} R_{irjt} - \sum_{k} S_{rkjt} \qquad \forall r, j, t \qquad (3.1)$$

$$\sum_{s} Q_{si\eta t} + \sum_{l} U_{li\eta t} = \sum_{r} \sum_{j} \left(R_{irjt} \right) v_{jn} \qquad \forall i, \eta, t$$
(3.2)

$$\sum_{i} R_{irjt} + I_{rjt} \ge \sum_{k} S_{rkjt} \qquad \forall r, j, t \qquad (3.3)$$

$$\sum_{r} S_{rkjt} \le d_{kjt} \qquad \forall k, j, t \qquad (3.4)$$

$$\sum_{r} S_{rkjt} \ge \sum_{l} T_{kljt} \qquad \forall k, j, t \qquad (3.5)$$

$$\sum_{l} T_{kljt} = z_{kjt} \qquad \forall k, j, t \tag{3.6}$$

$$\varepsilon_{\eta} \sum_{k} \sum_{j} (T_{kljt}) v_{j\eta} \le \lambda_{l\eta t} \qquad \qquad \forall l, \eta, t \qquad (3.7)$$

$$\sum_{k} \sum_{j} \left(T_{kljt} \right) v_{j\eta} = \sum_{i} U_{li\eta t} + \lambda_{l\eta t} \qquad \forall l, \eta, t \qquad (3.8)$$

$$\sum_{s} \sum_{\eta} \mathcal{Q}_{si\eta t} + \sum_{l} \sum_{\eta} U_{li\eta t} \leq V_{i} \sum_{\eta} g_{i\eta} \qquad \forall i, t \qquad (3.9)$$

$$\sum_{i} \sum_{j} R_{irjt} + \sum_{j} I_{rjt} \le W_r \sum_{j} h_{rj} \qquad \forall r, t \qquad (3.10)$$

$$\sum_{k} \sum_{j} T_{kljt} \leq X_l \sum_{j} n_{lj} \qquad \forall l, t \qquad (3.11)$$

$$\sum_{i} \sum_{\eta} Q_{si\eta t} \le Y_s \sum_{\eta} u_{s\eta} \qquad \qquad \forall s, t \qquad (3.12)$$

$$V_i, W_r, X_l, Y_s \in \{0, 1\} \qquad \qquad \forall i, r, l, s \qquad (3.13)$$

$$Q_{si\eta t}, R_{irjt}, S_{rkjt}, T_{kljt}, U_{l\eta t}, I_{rjt}, \lambda_{l\eta t} \ge 0 \qquad \forall s, i, \eta, t, r, j, k, l$$

$$(3.14)$$

The objective function is aimed to maximize the total profit in the battery CLSC network. The first part is associated with net revenue of selling product which is defined as the subtraction of transportation cost between retailers and markets from gross revenue obtaining from selling products to the market. The next part includes purchasing and shipping costs of components from suppliers to the plants. Cost of manufacturing and transportation between the plants and the retailers are two types of cost imposed to the production phase. It is assumed that the retailers deal with two types of cost consisting of inventory holding cost and transportation cost of products from the retailers to the markets. The next part of objective function is implied the shipping cost of used batteries from the markets to the battery recovery centers. According to the assumption, used batteries are decomposed to the product recovery. The next section is the costs associated with carrying unrecoverable components from the battery recovery centers to the disposal center and disposal cost. Furthermore, the total fixed-costs related to the location of suppliers, plants, retailers, battery recovery centers are mentioned respectively in the objective function.

Constraint (3.1) is related to the inventory in period *t* comprising of inventory in last period (*t*-1), and difference between the quantity of products shipping from the plants to the retailers (R_{irjt}), and selling to the market (S_{rkjt}) in period *t*. The left part of Constraint (3.2) implies the summation of components either purchasing from suppliers or coming from battery recovery

centers which should be equal to the number of components of products manufactured by plants. Constraint (3.3) obligates retailers to request products and keep the inventory either equal or greater than the selling products to the customers. Constraint (3.4, 3.5, 3.6) consider the trade-off between the selling products, the markets' demand and the returned products. Constraint (3.7) indicates the disposal fraction of the returned products. Constraint (3.8) is the trade-off between the components of returned products and recycled components shipping back to the plants along with unrecoverable components sending to the disposal center. Constraint (3.9) specifies the restriction in the capacities of plants for the components purchasing from suppliers and coming from battery recovery centers. Constraint (3.10) is related to the capacities of the retailers for the batteries produced by the plants and holding inventory in period *t*. Constraint (3.11) is associated with the capacities of the battery recovery centers for returned products. Similarly, Constraint (3.12) is related to the capacities of the suppliers to provide components η for plants. Finally, constraints (3.13) and (3.14) represent binary and non-negative decision variables.

3.4. Application of the proposed model and solution approach

The model has been applied for a battery CLSC network in Vancouver, Canada. The Vancouver municipality areas have been indicated in Fig. 3.2. There are 22 areas in Vancouver that each of them has been assumed as a demand market. In addition, 5 suppliers, 6 locations for plants, 7 locations for retailers, 10 locations for battery recovery centers, and 1 location for disposal center have been considered. Google Maps have been utilized to calculate the distances among the echelons (suppliers, plants, retailers, demand markets, battery recovery centers, and disposal center). The demand value of market *k* related to product *j* (d_{kjt}) has been assumed as one percent of the population of each municipality area based on 2011 census of Canada. The return value of market *k* for product *j* in each period *t* (z_{kjt}) has been considered as ten percent of each market demand. Furthermore, other values related to the parameters applied to solve the proposed model are indicated in Table 3.1.

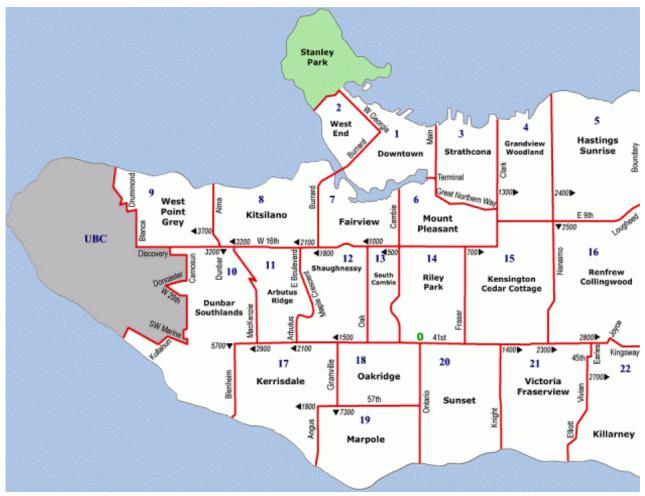


Fig. 3.2. Vancouver municipality areas

Table 3.1.											
Values of para	Values of parameters that have been applied to solve the proposed model										
J = 3	$A_s = 1,000$	$\varepsilon_{\eta} = 0.10$									
N = 5	$B_i = 1,000,000$	$P_{j} = 15$									
S = 5	$R_r = 1,500$	$f_{\eta} = 1$									
I = 6	$C_l = 1,500$	$g_{i\eta} = (2,500,000)_{6*5}$									
R = 7	$\delta_j = 150$	$h_{rj} = (10,000)_{7*3}$									
K = 22	$G_j = H_j = M_j = 0.097$	$n_{lj} = (10,000)_{10*3}$									
L = 10	$F_{\eta} = O_{\eta} = heta_{\eta} = 0.0194$	$u_{s\eta} = (30,000)_{5*5}$									
T = 3	$a_{\eta} = 10$	$\alpha_j = 40$									

IBM ILOG CPLEX 12.7.1.0 is utilized to solve the mathematical model. The model is solved in 2.84 seconds. There are 797 constraints, 3,560 single variables, 28 binary variables, and 28,569 non-zero coefficients. The results are written in Table 3.2.

Table 3.2 Solution for the proposed battery CLSC

	1 for the propose Opt	imal value		Binary variables (Y_s, V_i, W_r, X_l)
Objecti	ive	19,031,81	4.21	
$Q_{si\eta t}$	206,466.82	Period 1:	0	
Sint	200,100.02	Period 2:	206,466.82	Supplier Location (Y_s): Y_1 (Downtown), Y_5
<i>Rirjt</i>	57,655.90	Period 1:	8,181.27	(Downtown)
	,	Period 2:	49,474.635	
S _{rkjt}	181,536	Period 1:	90,768	Plant Location (V_i): V_2 (Downtown)
Стқл	101,000	Period 2:	90,768	
T_{kljt}	18,180.60	Period 1:	9,090.3	Retailer Location (W_r): W_1 (Strathcona) W_2
1 kijt	10,100.00	Period 2:	9,090.3	(Strathcona), W_3 (Grandview Woodland), W_4
$U_{li\eta t}$	81,812.70	Period 1:	40,906.35	(Grandview Woodland), W_7 (Downtown)
C lini	01,012.70	Period 2:	40,906.35	
		Period 0:	165,173.46	Battery recovery center location (X_l) : X_3
Irt	289,053.55	Period 1:	82,586.73	(Strathcona), X_5 (Renfrew- Collinwood)
		Period 2:	41,293.365	
λlηt	9,090.3	Period 1:	4,545.15	
νιηt	2,020.3	Period 2:	4,545.15	

3.5. An extension to consider uncertainty

In real life, most of parameters are imprecise due to uncertain environment. In this part, it is tried to take into account the impacts of uncertain demand and return on a battery CLSC profit. Hence, scenario-based analysis is applied to identify a solution associated with any random parameters. In this sense, discrete scenarios are utilized to cover different random variables on account of addressing uncertainty. For further information, it is suggested to refer to Snyder, 2006; Amin and Zhang, 2013; Al-Othman et al., 2008.

It is assumed that Problem 3.15 is solved to maximize the objective function. In this problem x and y are assumed as non-negative and binary variables, respectively. d, \dot{c} , and \dot{g} are defined vectors associated with selling price, variable, and fixed costs. Accordingly, \dot{a} , \dot{b} , \dot{e} , and \dot{f} are assumed as matrices.

 $\operatorname{Max} z = (\dot{d} \cdot \dot{c}) x - \dot{g} y$

s.t.

$$\begin{aligned} \dot{a} & x \leq b \\ \dot{e} & x \leq \dot{f} \\ \dot{y} \\ \dot{y} \in \{0,1\} \\ x \geq 0 \end{aligned}$$
 (3.15)

It is assumed that there are Ω scenarios which may happen by the probability of Φ_{ω} . Therefore, Problem 3.15 can be written as follows:

$$\begin{aligned} \operatorname{Max} & z = \sum_{\omega} \Phi_{\omega} \left(d_{\omega} - \dot{c}_{\omega} \right) x_{\omega} - \dot{g} \, Y \\ \text{s.t.} \\ & \dot{a}_{\omega} \, x_{\omega} \leq \dot{p}_{\omega} \quad \forall \, \omega, \\ & \dot{e}_{\omega} \, x_{\omega} \leq \dot{f} \, Y \quad \forall \, \omega, \\ & Y \in \{0,1\} \, x_{\omega} \geq 0 \, \forall \, \omega, \end{aligned}$$

$$(3.16)$$

In order to address the uncertainty of demand and return in the proposed battery CLSC, the following new set, parameters, and decision variables are defined.

3.5.1. Scenario-based analysis

Set

 Ω = set of scenarios (1 ... ω ... Ω)

Parameters

 $d_{kjt\omega}$ = number of demand from customer (market) k for product j related to period t in scenario ω $z_{kjt\omega}$ = number of returned product j from customer (market) k related to period t in scenario ω Φ_{ω} = probability of scenario ω

Decision Variables

 $Q_{si\eta t\omega}$ = number of components η shipped to plant *i* by supplier *s* related to period *t* in scenario ω $R_{irjt\omega}$ = number of product *j* produced by plant *i* for retailer *r* related to period *t* in scenario ω $S_{rkjt\omega}$ = number of product *j* sold by retailer *r* to customer *k* related to period *t* in scenario ω $T_{kljt\omega}$ = number of returned product *j* from customer *k* to recovery center *l* related to period *t* in scenario ω

 $U_{li\eta t\omega}$ = number of components η shipped to plant *i* from recovery center *l* related to period *t* in scenario ω

 $\lambda_{l\eta t\omega}$ = number of components η shipped to disposal center from recovery center l related to period t in scenario ω

 $I_{rjt\omega}$ = number of product *j* holding as the inventory in retailer *r* related to period *t* in scenario ω

$$\begin{aligned} &Max \ z_{1} = \sum_{\omega} \sum_{r} \sum_{k} \sum_{j} \sum_{t} \Phi_{\omega}(\delta_{j} - H_{j}E_{rk}) S_{rkjt\omega} - (\sum_{\omega} \sum_{s} \sum_{i} \sum_{\eta} \sum_{t} \Phi_{\omega}(N_{s\eta} + F_{\eta}E_{si}) Q_{si\eta t\omega} + \\ &\sum_{\omega} \sum_{i} \sum_{r} \sum_{j} \sum_{t} \Phi_{\omega}(P_{j} + G_{j}E_{ir}) R_{irjt\omega} + \sum_{\omega} \sum_{r} \sum_{t} \sum_{j} \Phi_{\omega}\alpha_{j}I_{rtj\omega} + \sum_{\omega} \sum_{k} \sum_{l} \sum_{j} \sum_{t} \Phi_{\omega}M_{j}E_{kl}T_{kljt\omega} + \\ &\sum_{\omega} \sum_{l} \sum_{i} \sum_{\eta} \sum_{t} \Phi_{\omega}(-a_{\eta} + O_{\eta}E_{li}) U_{li\eta t\omega} + \sum_{\omega} \sum_{l} \sum_{\eta} \sum_{t} \Phi_{\omega}(f_{\eta} + \theta_{\eta}E_{l})\lambda_{l\eta t\omega} + \\ &\sum_{s} A_{s}Y_{s} + \sum_{i} B_{i}V_{i} + \sum_{r} R_{r}W_{r} + \sum_{l} C_{l}X_{l}) \end{aligned}$$

s.t.

$$I_{rjt\omega} = I_{rjt-1\omega} + \sum_{i} R_{irjt\omega} - \sum_{k} S_{rkjt\omega} \qquad \forall r, j, t, \omega$$
(3.17)

$$\sum_{s} Q_{si\eta t\omega} + \sum_{l} U_{li\eta t\omega} = \sum_{r} \sum_{j} (R_{irjt\omega}) v_{jn} \qquad \forall i, \eta, t, \omega$$
(3.18)

$$\sum_{i} R_{irjt\omega} + I_{rjt\omega} \ge \sum_{k} S_{rkjt\omega} \qquad \forall r, j, t, \omega$$
(3.19)

$$\sum_{r} S_{rkjt\omega} \le d_{kjt\omega} \qquad \forall k, j, t, \omega$$
(3.20)

$$\sum_{r} S_{rkjt\omega} \ge \sum_{l} T_{kljt\omega} \qquad \forall k, j, t, \omega$$
(3.21)

$$\sum_{l} T_{kljt\omega} = z_{kjt\omega} \qquad \forall k, j, t, \omega$$
(3.22)

$$\varepsilon_{\eta} \sum_{k} \sum_{j} (T_{kljt\omega}) v_{j\eta} \leq \lambda_{l\eta t\omega} \qquad \forall l, \eta, t, \omega$$
(3.23)

$$\sum_{k} \sum_{j} (T_{kljt\omega}) v_{j\eta} = \sum_{i} U_{li\eta t\omega} + \lambda_{l\eta t\omega} \qquad \forall l, \eta, t, \omega$$
(3.24)

$$\sum_{s} \sum_{\eta} Q_{si\eta t\omega} + \sum_{l} \sum_{\eta} U_{li\eta t\omega} \leq V_{i} \sum_{\eta} g_{i\eta} \qquad \forall i, t, \omega$$
(3.25)

$$\sum_{i} \sum_{j} R_{irjt\omega} + \sum_{j} I_{rjt\omega} \le W_r \sum_{j} h_{rj} \qquad \forall r, t, \omega$$
(3.26)

$$\sum_{k} \sum_{j} T_{kljt\omega} \leq X_{l} \sum_{j} n_{lj} \qquad \forall l, t, \omega$$
(3.27)

$$\sum_{i} \sum_{\eta} Q_{si\eta t\omega} \le Y_s \sum_{\eta} u_{s\eta} \qquad \forall s, t, \omega$$
(3.28)

$$V_i, W_r, X_l, Y_s \in \{0, 1\} \qquad \qquad \forall i, r, l, s \qquad (3.29)$$

$$Q_{sint\omega}, R_{irjt\omega}, S_{rkjt\omega}, T_{kljt\omega}, U_{lint\omega}, I_{rjt\omega}, \lambda_{lnt\omega} \ge 0 \qquad \forall s, i, \eta, t, r, j, k, l, \omega$$
(3.30)

3.5.2. Computational results

Scenario-based analysis is performed to identify the effects of uncertain demand and return on the proposed battery CLSC profit. According to the assumption, the value of market's demand and returned products in Scenario 5 is assumed the same as deterministic model in Section 3.4. As a matter of fact, all possible combinations of 10 percent changes in market's demand and returned products are considered. As indicated by Table 3.3, the values of objective functions are compared with regard to Scenario 5 (e.g. change% in Scenario 1: (20,770,924.86-19,031,814.217) /19,031,814.217=9.14%). Furthermore, the scenario-based model (comprising of 7,165 constraints, 32,032 non-negative variables, 28 binary variables) is applied, and the results are indicated in Table 3.3 as well. The scenario-based model is assumed to include all possible 9 scenarios with probability of 0.075, 0.075, 0.1, 0.1, 0.3, 0.1, 0.1, 0.075, 0.075, respectively. The total expected profit of the 9 scenarios and the scenario-based model have been depicted in Fig. 3.3.

As shown in Table 3.3, comparing the objective values of the provided scenarios verifies that the profit of the battery CLSC is very sensitive to the alteration of market's demand and returned products. Accordingly, increasing the market's demand by 10 percent leads to increase the profit of the CLSC by 9.82% percent, while decreasing the market's demand by 10 percent leads to reducing the profit of CLSC by 9.83%.

Furthermore, it is noticeable that the impact of alteration in market's demand is more than the returned products on the profit of the CLSC. The proposed scenario-based model indicates the consideration of risks associated with different combinations of demand and return.

A	scenarios and scenario	o-based model		
Scenarios	Demand change%	Return change%	Total expected profit	change %
1	10% increase	10% decrease	20,770,924.86	9.14%
2	10% decrease	10% increase	17,292,004.647	-9.14%
3	No change	10% increase	19,162,255.752	0.69%
4	No change	10% decrease	18,901,372.683	-0.69%
5 (base-case)	No change	No change	19,031,814.217	0.00%
6	10% increase	No change	20,901,366.394	9.82%
7	10% decrease	No change	17,161,541.565	-9.83%
8	10% increase	10% increase	21,031,807.92	10.51%
9	10% decrease	10% decrease	17,031,121.578	-10.51%
10 (scenario-based	Combination of nin	e scenarios	19,030,998.425	-0.0043%
model)				

Table 3.3

25,000,000 20,000,000 **Total Expected Profit** 15,000,000 10,000,000 5,000,000 10^{(scenatior...} 0 5 Unservase) \$ \mathcal{V} ზ 6 \checkmark θ Scenario

Fig. 3.3. Total expected profit of 9 scenarios and the scenario-based model

3.5.3. Sensitivity analysis

As defined in Section 3.1, ε_{η} is the disposal fraction of components η . In order to consider the impact of efficiency in recycling on the profit of the CLSC, sensitivity analysis is applied. As indicated by Fig. 3.4, increasing the disposal fraction has reverse impact on the profit of the battery CLSC in both deterministic and scenario-based models. In other words, efficiency in recycling the components leads to higher profit for the CLSC.

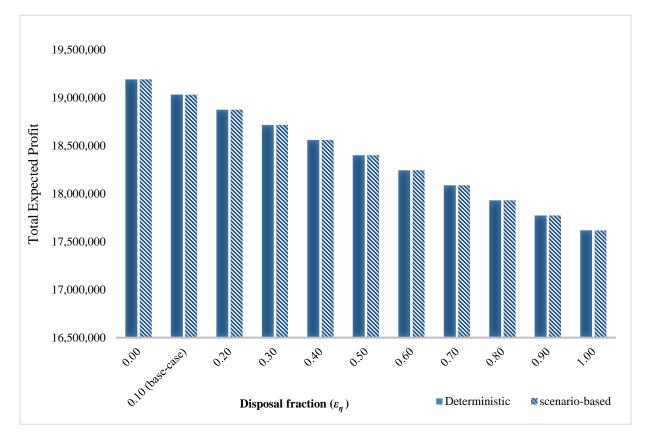


Fig. 3.4. Sensitivity analysis of disposal fraction (ε_{η})

3.6. Conclusions

In this chapter, a deterministic model for a battery CLSC has been introduced. The proposed model has considered multi-echelon, multi-component, multi-product CLSC in multiple periods. To display the application of the proposed model, a realistic network has been applied. According to the assumptions, 5 suppliers, 6 locations for plants, 7 retailers, and 10 locations for battery recovery centers were considered. The distance between echelons located in Vancouver was estimated through the google map. The solution for the proposed deterministic model indicated the objective optimal values, and decision variables with regard to multiple periods.

Furthermore, the optimal binary variables included 2 suppliers, 1 location for plant, 5 retailers, and 2 locations for battery recovery centers. The introduced model has been evaluated for different scenarios of unexpected changes in demand and return through utilizing scenario-based analysis.

The sensitivity analysis has indicated that how efficiency (lower disposal fraction) can have impact on the battery CLSC profit. In other words, if the battery recovery centers recycle more components, plants can produce more batteries with recycled materials leading to reduce the cost of purchasing raw material from suppliers. Therefore, reverse flow consisting of collecting and recycling returned products can enhance CLSC profit, and reduce the environmental issues.

There are some potential complementary research areas. In this chapter, scenario-based analysis has been utilized to evaluate the proposed model under uncertain circumstances. In this method, the possibility of occurrence of each scenario can be determined by the probability function of each scenario ($\Phi\omega$) which can be obtained based on judgment of decision makers. However, in some cases, there is not adequate information to estimate the probability of each scenario. Hence, other types of methods such as fuzzy programming and robust optimization are suggested to be applied as the supplement of scenario-based analysis to address uncertainty.

CHAPTER 4. APPLICATION OF FUZZY ANP TO RANK PLANTS AND BATTERY RECOVERY CENTERS BASED ON GREEN PERFORMANCE

4.1. Introduction

Nowadays, green practices are an essential part of company's affairs due to environmental regulatory compliance. Hence, green closed-loop supply chain management (GCLSC) can be defined as the integration of environmental management with CLSC including eco-product design, utilization of eco-intelligent technology, green purchasing, sustainable packaging, environmental practice, and recycling to fulfill customer's demand by sustainable products and services with less environmental impacts. In addition, there are a variety of green performance indicators which are considered thoroughly in the part of review of related studies. In order to evaluate the effectiveness of GCLSC, companies are usually required to apply decision making techniques. In this way, utilization of fuzzy sets theory for the purpose of combination with decision making techniques may be beneficial in the case of existing ambiguity in the expert preferences. Therefore, in order to pay adequate attention to green operational strategy in GCLSC, fuzzy ANP method is utilized to rank plants and battery recovery centers based on green performance in this study.

Section 4.2 includes review of related studies to evaluate GSCM and green performance indicators. Section 4.3 provides some necessary information about fuzzy ANP and Chang's method. In Section 4.4, a framework consisting of four criteria and eleven sub-criteria is introduced to rank six plants based on green performance, and then related analyses are provided. In Section 4.5, three criteria and seven sub-criteria are identified to rank battery recovery centers. Finally, Section 4.6 is devoted to conclusions.

4.2. Review of some related studies to identify the green performance indicators

Uygun and Dede (2016) proposed a model to evaluate green supply chain management (GSCM) through an integrated fuzzy multi-criteria decision making (MCDM) technique. The proposed model included five criteria and 17 sub-criteria comprised of regulations, environmental performance and economic performance as the sub-criteria of green design; supplier-customer collaboration, enforcement of stakeholders and quality regulation as the sub-criteria of green purchasing; green manufacturing, green packaging and green stock politics as the sub-criteria of green transformation; organization of green logistic network, quality of

service, and quality of technology as the sub-criteria of green logistic; reducing activities, recycling, remanufacturing, reusing, and disposal as the sub-criteria of reverse logistic.

Kusi-sarpong et al. (2016) introduced a framework to evaluate the impact of GSCM on organizational sustainable performance in mining industry. The proposed GSCM factors included green information technology and system (GITS), strategic supplier's partnership (SSP) operations and logistic integration (OLI), internal environmental management (IEM), eco-innovation practice (EOL), and end-of-life practices (EOL). Entezaminia et al. (2016) investigated the relationship between green principals and economic performance. In the proposed model recyclability, biodegradability, energy consumption, and product risk were determined as the environmental factors.

Miroshnychenko et al. (2017) investigated the impact of green practices comprised of ISO 14001, pollution prevention, and green product development on financial performance. They determined nitrogen dioxide, emission reduction, waste reduction, water and energy efficiency, and toxic chemical reduction as the factors to measure pollution prevention index, while environmental products and eco-product design were considered as the indicators of green product index. Sharma et al. (2017) utilized AHP method to rank 13 green performance factors and 79 sub-factors for GSCM. According to their findings, environmental management and design, regulatory pressure, and green purchasing were determined as the most effective green performance indicators.

Vanalle et al. (2017) indicated that environmental practice and economic performance have a positive relationship by application of partial least squares structural equation modeling (PLS-SEM). Internal environmental issues (IEM), eco-design, green purchasing, collaboration with customers regarding environmental issues and investment recovery were determined as the indicators for GSCM practice in their study. Sari (2017) introduced a framework to evaluate GSCM by utilizing Monte Carlo simulation and AHP method. The green practices in inbound operation, production operation, outbound operation and reverse logistic were considered to assess the performance of GSCM. For such evaluation, designing recyclable products and utilization of cleaner technology were assigned as the sub-factors for green production operation. Choosing suppliers based on environmental criteria, green purchasing, and cooperation with suppliers to develop environmental practices were determined as the indicators for green inbound operation. Carvalho et al. (2017) proposed a model to determine the best set of green

performance and lean supply chain management practices with the aim of promoting ecoefficiency in automotive industry. In the proposed framework, ISO 14001 and environmentally friendly packaging were considered as the indicators for green performance. Zhao et al. (2107) proposed a multi-objective model for the optimization of an GSCM network. They minimized the risk arising from hazardous materials, and carbon emission.

Tramarico et al. (2017) utilized AHP method to evaluate GSCM through four top-level criteria including plan, source, make, and deliver. In the proposed framework, sub-criteria of plan were considered as the planning for demand based on long-term basis, and planning for material with the best use of resource. Sub-criteria of source were identified as the usage of recycled raw material, and merchandizing based on renewable energy. Besides, sub-criteria of make were comprised of reducing the scrap rate, reducing the greenhouse gas emission, recycling and reusing water, and sub-criteria of deliver were chosen as the application of full truckload for distribution, and reducing the environmental impacts through the transportation management.

Scur and Barbosa (2017) examined the application of green practices in the home appliance industry. The proposed framework for green practices consisted of internal environmental management, green purchasing and manufacturing, eco-design, and waste management. According to their findings, waste management was the most widely applied practice between research participants.

4.3. Fuzzy ANP

Saaty (1996) introduced analytic network process (ANP) as the modified form of analytic hierarchy process (AHP) to deal with interrelationship among factors affecting in making decision. ANP was developed by synthesizing with fuzzy sets theory with the aim of dealing with ambiguity in expert preferences. Hence, fuzzy ANP and triangular fuzzy numbers (TFNs) have become integrated on account of coping with uncertainty. In this study, Chang's method (1996) is utilized to rank the green performance of plants and battery recovery centers.

As illustrated in Fig. 4.1, TFNs can be indicated by membership function which is between 0 and 1.

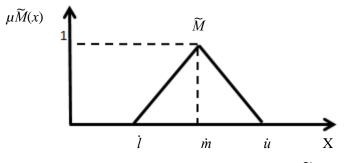


Fig. 4.1. A triangular fuzzy number \widetilde{M} .

If \widetilde{M} is assumed as an TFN by three components such as $\widetilde{M} = (\dot{l}, \dot{m}, \dot{u})$, the associated membership function is written by Eq. (4.1).

$$\mu M(x) = \begin{cases} 0, x < \dot{l}, & (4.1) \\ \frac{x - \dot{l}}{\dot{m} - \dot{l}}, \dot{l} \le x \le \dot{m}, \\ \frac{\dot{u} - x}{\dot{u} - \dot{m}}, \dot{m} \le x \le \dot{u}, \\ 0, x > \dot{u}, \end{cases}$$

To apply the pairwise comparisons through the fuzzy ANP method, the Chang's extent examination is utilized.

Step 1: Eq. (4.2) indicates the value of fuzzy synthetic extent considering the i^{th} object. In this way, the value of $\sum_{i} \tilde{M}_{gi}^{j}$ can be obtained from Eq. (4.3).

$$\dot{S}_{i} = \sum_{j} \tilde{M}_{gi}^{j} \otimes \left[\sum_{i} \sum_{j} \tilde{M}_{gi}^{j} \right]^{-l}$$

$$(4.2)$$

$$\sum_{j} \tilde{M}_{gi}^{j} = \left(\sum_{j} \dot{l}_{j}, \sum_{j} \dot{m}_{j}, \sum_{j} \dot{u}_{j}\right)$$
(4.3)

Where all the \widetilde{M}_{gi}^{j} are assumed triangular fuzzy numbers.

Step 2: to compare the fuzzy numbers, it is required to calculate the degree of possibility for $\widetilde{M}_1 \ge \widetilde{M}_2$, which can be defined by Eq. (4.4).

$$V(\widetilde{M}_{1} \ge \widetilde{M}_{2}) = \sup \left[\min(\mu \widetilde{M}_{1}(x), \mu \widetilde{M}_{2}(y))\right]$$

$$x \ge y$$
(4.4)

According to assumptions, if there is a pair of (x, y) and $x \ge y$, while $\mu \widetilde{M}_1(x) = \mu \widetilde{M}_2(y)=1$, then $V(\widetilde{M}_1 \ge \widetilde{M}_2) = 1$. It is assumed that $\widetilde{M}_1 = (\dot{l}_1, \dot{m}_1, \dot{u}_1)$ and $\widetilde{M}_2 = (\dot{l}_2, \dot{m}_2, \dot{u}_2)$ are convex fuzzy numbers.. Therefore Eq. (4.5) can be written as follows.

$$V(\widetilde{M}_{l} \ge \widetilde{M}_{2}) = 1 \qquad \text{if } \dot{m}_{l} \ge \dot{m}_{2},$$

$$V(\widetilde{M}_{2} \ge \widetilde{M}_{l}) = hgt(\widetilde{M}_{l} \cap \widetilde{M}_{2}) = \mu \widetilde{M}_{l}(d) \qquad (4.5)$$

As illustrated by Fig. 4.2, \dot{d} is the ordinate of the highest intersection point *D* between $\mu \tilde{M}_1$ and $\mu \tilde{M}_2$, which can be obtained from Eq. (4.6).

$$V(\widetilde{M}_{2} \geq \widetilde{M}_{1}) = hgt(\widetilde{M}_{1} \cap \widetilde{M}_{2}) = \frac{\dot{l}_{1} - \dot{u}_{2}}{(\dot{m}_{2} - \dot{u}_{2}) - (\dot{m}_{1} - \dot{l}_{1})}$$

$$V(\widetilde{M}_{2} \geq \widetilde{M}_{1})$$

$$V(\widetilde{M}_{2} \geq \widetilde{M}_{1})$$

$$I_{2}$$

$$\dot{m}_{2}$$

$$\dot{l}_{1}$$

$$\dot{d}$$

$$\dot{u}_{2}$$

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$$\dot{m}_{3}$$

$$\dot{m}_{4}$$

$$\dot{m}_{4}$$

$$\dot{m}_{5}$$

$$\dot{m}_{$$

In order to apply the comparisons between \widetilde{M}_1 and \widetilde{M}_2 , it is required to have the both values of V $(\widetilde{M}_1 \ge \widetilde{M}_2)$ and V $(\widetilde{M}_2 \ge \widetilde{M}_1)$. Generally, if there are *k* TFNs, the degree of possibility can be estimated as follows:

$$V(\widetilde{M} \ge \widetilde{M}_{I}, \widetilde{M}_{2}, ..., \widetilde{M}_{k}) = V[(\widetilde{M} \ge \widetilde{M}_{I}) \text{ and } (\widetilde{M} \ge \widetilde{M}_{2}) \text{ and } ... \text{ and, } (\widetilde{M} \ge \widetilde{M}_{k})]$$

$$= \min V(\widetilde{M} \ge \widetilde{M}_{i}), i = 1, 2, ..., k$$

$$(4.7)$$

$$d'(A_i) = \min V(S_i \ge S_k), \tag{4.8}$$

The weight vector can be written by Eq. (4.9) for k = 1, 2, ..., n and $k \neq i$

$$W' = (d'(\dot{A}_1), d'(\dot{A}_2), \dots, d'(\dot{A}_n))^{\mathrm{T}},$$
(4.9)

Where \dot{A}_i (*i* = 1, 2, ..., *n*) are *n* elements. Thereafter, Eq. (4.9) is replaced by Eq. (4.10) after normalization.

$$W = (d(\dot{A}_1), d(\dot{A}_2), \dots, d(\dot{A}_n))^{\mathrm{T}},$$
(4.10)

4.4. ANP model to determine plants priority based on green performance

In this section, it is aimed to prioritize potential plants based on green performance through the fuzzy ANP method. As indicated by Fig. 4.3, some associated criteria and sub-criteria are identified based on the related literatures and websites of battery plants and recovery centers (Sorting and processing, 2017; how to recycle battery, 2012).

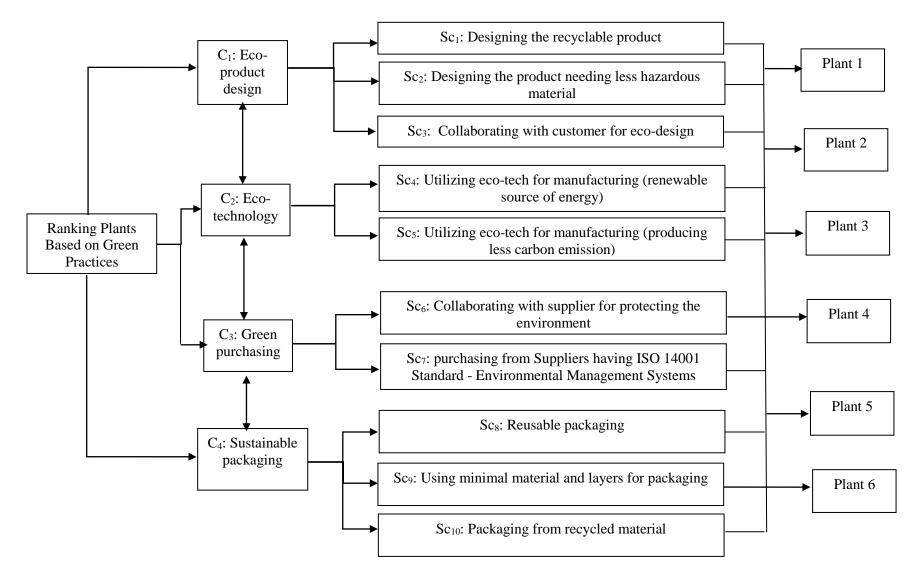


Fig. 4.3. The ANP model for prioritizing plants based on their green performance

4.4.1. Criterion 1: Eco-product design

The advantages of eco-product design have been realized in CLSC. In addition, market demand is the other factor to stimulate manufacturers to utilize eco-design in production. In this study, it is intended to consider three sub-factors for eco-design as follows:

4.4.1.1. Sub- criterion 1: Designing the recyclable product

According to many studies, recyclable products can increase the profits of CLSCs. Amin and Zhang (2013), Rao and Holt (2005) indicated that there is a relationship between the rate of returned product, and improving the economic performance of supply chains.

4.4.1.2. Sub- criterion 2: Designing the product needing less hazardous material

According to various regulations, manufacturers have been prohibited to design the products containing toxic materials for humans and environment. For instance, production of mercury batteries has been significantly reduced due to the legislation of Mercury-Containing and Rechargeable Battery Management Act in 1996.

4.4.1.3. Sub- criterion 3: Collaborating with customers for eco-design

There is no doubt that customer's needs and expectations should be always prioritized. For such reasons, collaborating with customers in eco-design may develop the relationships between customers and companies leading to emerge the customer loyalty.

4.4.2. Criterion 2: Utilizing eco-technology

Application of eco-technology has been more popular on account of benefit, and preventing environmental issues. It is aimed to consider two sub-criteria for the factors of eco-technology to rank plants based on green performance.

4.4.2.1. Sub- criterion 4: Utilizing eco- technology in production (renewable source of energy)

Nowadays, companies are encouraged to utilize renewable energy in production such as wind and water power or solar energy. The renewable energy can be applied in production (in case of producing electricity), heating and cooling (for the process), and in transportation sector.

4.4.2.2. Sub- criterion 5: Utilizing eco-tech for manufacturing (producing less carbon emission)

Carbon emission or greenhouse gasses including carbon dioxide and carbon monoxide are released to environment mostly from plants and transportation sector. Accumulated carbon emission in the atmosphere reflect the heat to the ground surface which contributes to the global warming. To prevent the environmental impacts of using technology, it is recommended to replace old technology using inefficient fossil fuel by modern eco-technology releasing less carbon emission.

4.4.3. Criterion 3: Green purchasing

Green purchasing is defined as the collaboration with suppliers to produce and develop the products which are environmentally sustainable. In this step, two sub-criteria are categorized under green purchasing as follows:

4.4.3.1. Sub- criterion 6: Collaborating with supplier for protecting the environment

Process of purchasing products from supplier can be supplemented with environmental design which may facilitate recycling process and decreasing the scrap rate of returned products. In this way, providing material specifications to the suppliers based on environmental concerns can decrease waste material and benefit environment.

4.4.3.2. Sub- criterion 7: Purchasing from suppliers having ISO 14001 standard -

environmental management systems

Nowadays, environmental concerns such as climate changes and contamination of soil and groundwater by hazardous industrial septic are growing as the mutual global concerns. ISO 14001 provided by International standards organization aims to help all types of businesses to have more sustainable operations. It provides comprehensive instruction in various aspects of businesses including procurement, manufacturing, transportation, and storage to have less impacts on environment.

4.4.4. Criterion 4: Sustainable packaging

Sustainable or eco-friendly packaging can be defined as the utilization of materials in packaging which are recyclable and reusable. Three sub-criteria are determined for sustainable packaging in this study.

4.4.4.1. Sub- criterion 8: Reusable packaging

Reusable packaging is a type of packaging which can be reused many times. This type of packaging is intentionally designed in terms of durability, reparability, and cleanability for multiple usages.

4.4.4.2. Sub- criterion 9: Using minimal material and layers for packaging

Application of minimal materials and layers in packaging is the most prominent factor in ecofriendly packaging which can diminish the waste materials significantly.

4.4.4.3. Sub- criterion 10: Packaging from recycled material

Some types of materials such as glasses, papers, metals, and cardboard can be recycled and go back to the same types of packaging for many times.

The steps (guidelines) to prioritise plants based on green performance are as follows:

Step 1: As illustrated in Fig. 4.3, the problem is converted to three levels. First, criteria (ecoproduct design, eco-technology, green purchasing, sustainable packaging), then sub-criteria (Sc_1 , ..., Sc_{10}), and finally alternatives (Plants 1 to 6) are defined.

Step 2: Pairwise comparisons are applied for the problem. The fuzzy linguistic scale written in Table 4.1 and Fig. 4.4 is utilized for the pairwise comparisons. Initially, it is assumed that there is no dependency among the criteria. The results of the pairwise comparisons by the given fuzzy scales for the criteria (We_1), are indicated in Table 4.2.

Table 4.1		
The linguistic scale		
Linguistic scale	TFNs	Reciprocal TFNs
Absolutely more important (AMI)	(5/2, 3, 7/2)	(2/7, 1/3, 2/5)
Very strongly more important (VSMI)	(2, 5/2, 3)	(1/3, 2/5, 1/2)
Strongly more important (SMI)	(3/2, 2, 5/2)	(2/5, 1/2, 2/3)
Weakly more important (WMI)	(1, 3/2, 2)	(1/2, 2/3, 1)
Equally important (EI)	(1/2, 1, 3/2)	(2/3, 1, 2)
Just equal	(1, 1, 1)	(1, 1, 1)

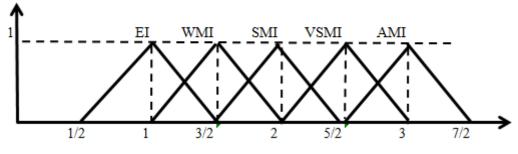


Fig. 4.4. Linguistic scale for relative importance

We_1		C_1			C_2			C_3			C_4		Local weights
C_1	(1	1	1)	(0.5	1	1.5)	(1	1.5	2)	(1.5	2	2.5)	0.337
C_2	(0.67	1	2)	(1	1	1)	(1	1.5	2)	(2.5	3	3.5)	0.402
C_3	(0.5	0.67	1)	(0.5	0.67	1)	(1	1	1)	(0.5	1	1.5)	0.152
C_4	(0.4	0.5	0.67)	(0.29	0.33	0.4)	(0.67	1	2)	(1	1	1)	0.109

Table 4.2 Pairwise comparisons among criteria

Step 3: As indicated in Fig. 4.5, there may be inner dependence between the factors. In this situation, the inner dependency among criteria can be measured by considering the effect of every criterion on every other through the pairwise comparisons. In this way, the following question may be asked: To what extend eco-technology could be more important compared to eco-product design with respect to sustainable packaging (see Tables 4.3 - 4.6). The results of the pairwise comparisons are presented in Table 4.7 which is related to the inner dependence matrix of green performance criteria (*We*₂).

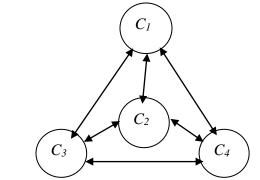


Fig. 4.5. Inner dependence between green performance criteria

Table 4.3
The inner dependence matrix and relative importance weight with respect to Eco-product design

Eco-product design	Eco	o-techn	ology	Gre	een pu	rchasing	I	Sustaina packag		Local weights
Eco-technology	(1	1	1)	(1	1.5	2)	(0.4	0.5	0.67)	0.293
Green purchasing	(0.5	0.67	1)	(1	1	1)	(0.5	0.67	1)	0.161
Sustainable packaging	(1.5	2	2.5)	(1	1.5	2)	(1	1	1)	0.546

Eco-technology			design	Green purchasing Sustainable packag			0.	Local weights		
Eco-product design	(1	1	1)	(2	2.5	3)	(1	1.5	2)	0.602
Green purchasing	(0.33	0.4	0.5)	(1	1	1)	(0.5	1	1.5)	0.125
Sustainable packaging	(0.5	0.67	1)	(0.67	1	2)	(1	1	1)	0.273

 Table 4.4

 The inner dependence matrix and relative importance weight with respect to Eco-technology

Table 4.5

The inner dependence matrix and relative importance weight with respect to Green purchasing

Green purchasing	Eco-	produc	t design	lesign Eco-technology			Sustainable packaging			Local weights
Eco-product design	(1	1	1)	(1	1.5	2)	(1.5	2	2.5)	0.547
Eco-technology	(0.5	0.67	1)	(1	1	1)	(0.4	0.5	0.67)	0.077
Sustainable packaging	(0.4	0.5	0.67)	(1.5	2	2.5)	(1	1	1)	0.377

Table 4.6

The inner dependence matrix and relative importance weight with respect to Sustainable packaging

Sustainable packaging	Eco-p	oroduct	design	Eco-te	chn	ology	Green	ı pu	rchasing	Local weights
Eco-product design	(1	1	1)	(1.5	2	2.5)	(1.5	2	2.5)	0.614
Eco-technology	(0.4	0.5	0.67)	(1	1	1)	(0.5	1	1.5)	0.157
Green purchasing	(0.4	0.5	0.67)	(0.67	1	2)	(1	1	1)	0.229

Table 4.7

The inner dependence matrix of green performance criteria

We ₂	Eco-product	Eco-	Green	Sustainable
we ₂	design	technology	purchasing	packaging
Eco-product design	1	0.602	0.547	0.614
Eco-technology	0.293	1	0.077	0.157
Green purchasing	0.161	0.125	1	0.229
Sustainable packaging	0.546	0.273	0.377	1

Step 4: In this step, $We_{criteria}$ is calculated based on the inner dependence matrices We_1 and We_2 . The results are provided in Table 4.8.

Table 4.8

The relat	ted prioritie	es of the g	reen perfe	ormance	criteria
Wa	C	C	C	C	Wa

We_2	C_1	C_2	C_3	C_4	We_1	$We_{criteria} = We_2^* We_1$
C_1	1	0.602	0.547	0.614	0.337	0.365
C_2	0.293	1	0.077	0.157	0.402	0.265
C_3	0.161	0.125	1	0.229	0.152	0.141
C_4	0.546	0.273	0.377	1	0.109	0.230

Step 5: The priorities of the green performance sub-criteria are obtained based on pairwise comparisons. The local weights of sub-criteria are provided in Tables 4.9 - 4.12.

Pairwise comparisons among sub-criteria of Eco-product design										
Eco-product design		Sc_1			Sc_2			Sc3		Local weights
Sc_1	(1	1	1)	(2	2.5	3)	(1.5	2	2.5)	0.771
Sc_2	(0.33	0.4	0.5)	(1	1	1)	(0.5	1	1.5)	0.038
Sc ₃	(0.4	0.5	0.67)	(0.67	1.0	2)	(1	1	1)	0.191

Table 4.9

Table 4.10

Pairwise comparisons among sub-criteria of Eco-technology									
Eco- technology		Sc_4	Į.		Sc ₅		Local weights		
Sc_4	(1	1	1)	(0.5	0.67	1)	0.316		
Sc ₅	(1	1.5	2)	(1	1	1)	0.684		

Table 4.11

Doirwigo comparigone	among sub-criteria of G	roon nurchaging
r an wise comparisons	among sub-criticita of O	icen purchasing

Fairwise comp	arisons	among	sub-c	mena	of Glee	en puic	nasnig
Green		Sc ₆			Sc7		Local
purchasing		306			307		weights
Sc_6	(1	1	1)	(1	1.5	2)	0.684
Sc_7	(0.5	0.67	1)	(1	1	1)	0.316

Table 4.12

comparisons			

Sustainable packaging		Sc ₈			Sc ₉	-		<i>Sc</i> ₁₀		Local weights
Sc_8	(1	1	1)	(0.5	0.67	1)	(1.5	2	2.5)	0.405
Sc ₉	(1	1.5	2)	(1	1	1)	(1	1.5	2)	0.448
Sc_{10}	(0.4	0.5	0.67)	(0.5	0.67	1)	(1	1	1)	0.147

Step 6: The overall priorities related to the green performance sub-criteria are computed by multiplying $We_{criteria}$ (interdependent priorities of green performance criteria) obtained in Step 4, and the local weights of sub-criteria obtained in Step 5. The results are illustrated in Table 4.13.

Fuzzy ANP	<i>We_{criteria}</i> obtained in Step 4	Sub-criteria	<i>We_{sub-criteria}</i> obtained in Step 5	We _{sub-criteria,} (overall)
		Sc_1	0.771	0.281
C_1 : Eco-product design	0.365	Sc_2	0.038	0.014
		Sc_3	0.191	0.070
		Sc_4	0.316	0.084
C ₂ : Eco-technology	0.265	Sc_5	0.684	0.181
C. Crean muchasing		Sc_6	0.684	0.096
<i>C</i> ₃ : Green purchasing	0.141	Sc_7	0.316	0.044
		Sc_8	0.405	0.093
C4: Sustainable packaging	0.230	Sc_9	0.448	0.103
	0.230	Sc_{10}	0.147	0.034

Table 4.13Overall priority of the sub-criteria of green performance for potential plants

Step 7: The priorities of the potential plants with regard to each sub-criterion are computed by pairwise comparisons. The results are indicated in Table 4.14 (We_4), and the details of calculations are provided in Appendix A.

Table 4.14Overall priority of each plant associated with each sub-criterion

We_4	Sc_1	Sc_2	Sc3	Sc_4	Sc_5	Sc_6	Sc7	Sc_8	Sc ₉	Sc_{10}
Plant 1	0.211	0.232	0.262	0.262	0.312	0.198	0.270	0.214	0.235	0.225
Plant 2	0.183	0.219	0.206	0.169	0.156	0.212	0.184	0.229	0.181	0.184
Plant 3	0.186	0.177	0.157	0.168	0.155	0.151	0.145	0.135	0.179	0.187
Plant 4	0.149	0.111	0.185	0.153	0.185	0.180	0.126	0.145	0.127	0.148
Plant 5	0.158	0.142	0.112	0.142	0.133	0.134	0.157	0.175	0.156	0.157
Plant 6	0.111	0.121	0.078	0.106	0.058	0.124	0.118	0.102	0.122	0.099

Step 8: The overall priority of the potential plants based on green practices are measured by multiplying We_4 found in Step 7, and $We_{sub-criteria (overall)}$ obtained in Step 6. The results are provided in Table 4.15.

		2	ANP
ŀ	Plants	ANP	priority
1		0.242	1
2	2	0.186	2
3	;	0.166	3
4	Ļ	0.157	4
5	i	0.148	5
6	ō	0.100	6

Table 4.15Results of the fuzzy ANP method for the plants

4.5. ANP model to determine priority of battery recovery centers based on green performance

The overall priorities of the potential battery recovery centers in aspect of green performance are measured based on the same method utilized for ranking the potential plants. As illustrated in Fig. 4.6, 3 criteria and 7 sub-criteria have been identified in this part.

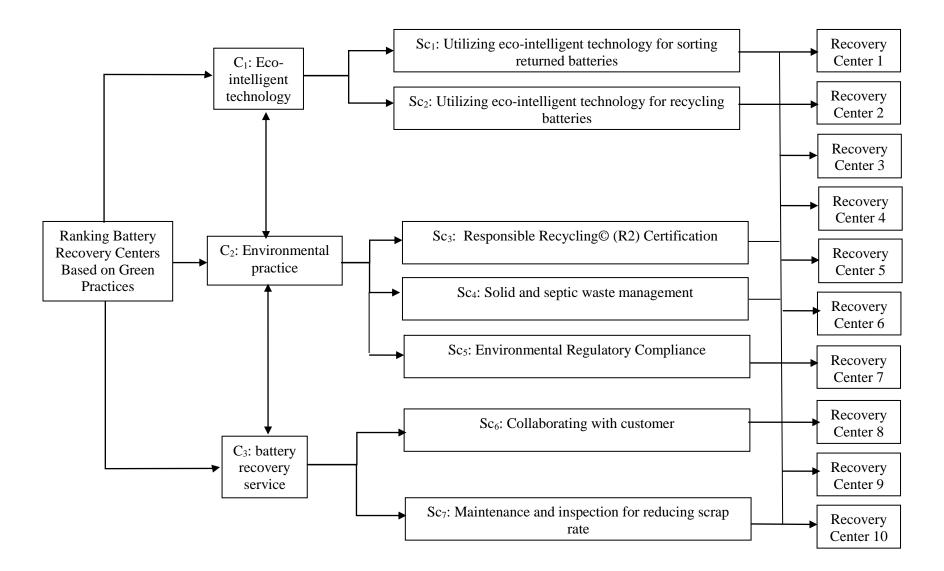


Fig. 4.6. The ANP model for prioritizing recovery centers based on their green performance

4.5.1. Criterion 1: Eco-intelligent technology

Process of battery recycling can be complicated on account of safety reasons and environmental impacts. In this way, eco-intelligent technology can be utilized to overcome these issues.

4.5.1.1. Sub- criterion 1: Utilizing eco-intelligent technology for sorting returned batteries

Sorting the returned batteries for the purpose of recycling needs broad knowledge and expertise. For instance, mixing the Alkaline batteries and mercury containing batteries is hazardous because of reusing recycled materials, or mixing Lithium batteries with Alkaline batteries may lead to fire occurrence. For such reasons, utilizing eco-intelligent technology is the significant help in the sorting section (www.batterysolutions.com).

4.5.1.2. Sub- criterion 2: Utilizing eco-intelligent technology for recycling batteries

Application of eco-intelligent technology allows recovery centers to recycle the returned batteries intelligently with less environmental impacts due to the usage of renewable source of energy.

4.5.2. Criterion 2: Environmental practice

Transparency and compliance of the recovery centers with the rules legislated to protect the environment can be an overriding factor for ranking them.

4.5.2.1. Sub- criterion 3: Responsible Recycling[©] (R2) Certification

The Responsible Recycling[©] (R2) Certification provided by the environmental protection agency (EPA) includes a variety of guidelines and principals to evaluate green performance of recyclers. It is necessary for battery recovery centers to show their commitments towards protecting environment. Obtaining such certification makes the battery recovery centers equipped to do the recycling process with less impact on environment.

4.5.2.2. Sub- criterion 4: Solid and septic waste management

Solid and septic waste management include all activities such as collecting, transporting, treating, and disposal of waste with regard to ratified regulation. Therefore, considering waste management is a critical subject due to the usage of chemical materials for the purpose of recycling in battery recovery centers.

4.5.2.3. Sub- criterion 5: Environmental Regulatory Compliance

Environmental compliance is defined as the obedience to ratified laws and regulations to protect environment. Battery recovery centers are supposed to comply with environmental regulations such as chemical use policy, mercury statement, and carbon footprint.

4.5.3. Criterion 3: Battery recovery service

Some of the battery recovery centers provide some services including preventive maintenance and free battery handling. In this category, two sub-factors such as collaborating with customers and maintenance for reduction of scrap rate are utilized for ranking the recovery centers.

4.5.3.1. Sub- criterion 6: Collaborating with customer

There are some services offered by recovery centers which can help customers such as installation of valve regulated battery, de-installation of lead battery, handling and removal of battery. All mentioned services can be the prominent factors to reduce discarded battery in environment.

4.5.3.2. Sub- criterion 7: Maintenance and inspection for reducing scrap rate

Preventive maintenance along with comprehensive inspection reports are offered by some of the battery recovery centers which may prolong life of the battery.

In order to rank the battery recovery centers, Step 1 to Step 8 were applied for green performance framework (Fig. 4.6). The details of the calculations are provided in Appendix B, and the results are indicated in Table 4.16.

Results of the fuzzy ANP method for the recovery ce										
Result	ANP	ANP priority								
Recovery center 1	0.148	1								
Recovery center 2	0.120	2								
Recovery center 3	0.102	5								
Recovery center 4	0.109	4								
Recovery center 5	0.116	3								
Recovery center 6	0.098	6								
Recovery center 7	0.071	9								
Recovery center 8	0.087	8								
Recovery center 9	0.092	7								
Recovery center 10	0.057	10								

Table 4.16. Results of the fuzzy ANP method for the recovery centers

4.6. Conclusions

In this chapter, some related literatures to find green performance indicators for evaluating GSCM have been provided. Thereafter, some necessary concepts about fuzzy ANP and Chang's method have been described comprehensively. Since, it is intended to consider the green practices of plants and battery recovery centers in the next chapters, two frameworks have been introduced. Firstly, a framework included four criteria and eleven sub-criteria has been proposed to rank the six plants based on green performance. Subsequently, three criteria and seven sub-criteria have been identified to rank battery recovery centers. In this way, fuzzy ANP has been utilized based on Chang's method. The necessary linguistic scale of relative importance along with related guidelines for doing pairwise comparison were provided. According to the instructions, all criteria were supposed to compare without considering the probable inner dependency. However, there could be relationship among criteria led to have impacts on final results. Therefore, pairwise comparisons were applied by considering the inner dependency among criteria. Thereafter, all sub-criteria were compared, and then all plants and battery recovery centers are provided in Appendices A and B.

CHAPTER 5. A POSSIBILISTIC SOLUTION TO CONFIGURE A BATTERY CLOSED-LOOP SUPPLY CHAIN: MULTI-OBJECTIVE APPROACH

5.1. Introduction

Nowadays, decision makers encounter challenges about imprecise information in design an optimization of supply chain models. Those ambiguities stem from either internal or external factors affecting model's profit or cost. In other words, most of information is not deterministic, and decision makers are supposed to reconcile their decisions with such uncertainties. In this sense, fuzzy programming plays a prominent role in optimization problems. If it is assumed that all parameters and decision variables are imprecise, the fuzzy programming can be extended to fully fuzzy programming (FFP) case. In this thesis, it is aimed to develop and apply FFP to address the probable uncertainty in the introduced battery CLSC network.

The structure of this chapter is arranged as follows: First, some literatures of fuzzy programming method are reviewed in Section 5.2. Subsequently, some necessary concepts and background of fuzzy arithmetic are provided in Section 5.3. Thereafter, FFP method is applied for the proposed battery CLSC network in Section 5.4. The values of parameters and solutions are provided in Section 5.5. To address uncertainty thoroughly, combination of scenario-based analysis and FFP is employed to consider different scenarios in Section 5.6. An extension to multi-objective is described in Section 5.7. The definition and application of distance method along with the results are provided in Section 5.8. The E-constraint method is also utilized for comparison the results with distance method in Section 5.9. Finally, Section 5.10 is devoted to conclusions.

5.2. Review of some related studies to fuzzy programming method

Kabak and Ülengin. (2011) applied possibilistic linear programming (PLP) in order to deal with uncertainties in their proposed model. For such purposes, a fuzzy sets theory-based model was used with the view of making strategic plan for utilizing resources under uncertainties. According to their assumption, some parameters of their proposed model were fuzzy, and the others were crisp. Ebrahimnejad et al. (2014) proposed a method in which parameters of the objective function and the values of the right-hand side related to constraints are complied with symmetric trapezoidal fuzzy numbers, while the other parameters are indicated by real numbers.

They also mentioned that their model needs less arithmetic operations. Furthermore, they retrieved a fuzzy solution from the converted crisp problem without adding constraints and variables to the original problems. Wan et al. (2014) proposed a fuzzy linear programming model consisting of trapezoidal fuzzy numbers (TrFNs). They used TrFNs to consider uncertainties for the imprecise parameters and decision variables existing in the objective functions, and the constraints. They applied auxiliary multi-objective linear programming (MOLP) in order to solve the possibilistic problems. Weighted-sum method, optimistic, and pessimistic approaches were utilised to solve the auxiliary MOLP. Azadeh et al. (2015) developed a multi-objective multi-period fuzzy programming model to consider different objectives under uncertain circumstances. Hence, a two-phase approach was introduced to solve the problem. First, a multi-objective method was applied to convert the multi-objective model into a single objective one. They applied a possibilistic programming approach to verify and validate their model.

Ezzati et al. (2015) proposed a new algorithm to solve the FFP problem with regard to new lexicographic ordering on triangular fuzzy numbers (TFNS). According to their novel algorithm, FFP was converted to its equivalent MOLP problem, and then it was solved by complying with lexicographic method. Dai et al. (2016) developed an interval fuzzy possibilistic programming (IFPP) by combining interval parameters programming (IPP), fuzzy possibilistic programming (FPP), and a fuzzy expected value equation. They claimed that the proposed method could deal with uncertainties and improve the conventional fuzzy mathematical programming.

5.3. An overview of triangular fuzzy number operations

In this part, some necessary concepts and backgrounds of fuzzy arithmetic are provided.

Definition 5.1. As indicated in Fig. 5.1, $\tilde{u} = (i, k, l)$ is a triangular fuzzy number, if its membership function is given as follows:

$$\mu_{u}(x) = \begin{cases} 0, & x < i \\ (x - i) / (k - i) & i \le x \le k \\ (l - x) / (l - k) & k \le x \le l \\ 0, & x > l \end{cases}$$
(5.1)

Definition 5.2. A triangular fuzzy set $\tilde{u} = (i, k, j)$ is assumed to be non-negative triangular fuzzy set, if and only if $i \ge 0$.

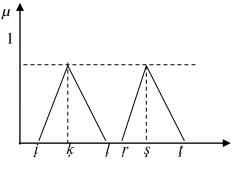


Fig. 5.1. A triangle fuzzy number

Definition 5.3. The arithmetic operations between two triangular fuzzy set $\tilde{u} = (i, k, j)$ and $\tilde{v} = (r, s, t)$ are indicated as follows

i. $n \ge 0, n \ \tilde{u} = (n i, n k, n i),$ (5.2)

ii.
$$n \le 0, n \ \tilde{u} = (n l, n k, n l),$$
 (5.3)

iii.
$$\tilde{u} + \tilde{v} = (i + r, k + s, l + t),$$
 (5.4)

iv.
$$\tilde{v} - \tilde{u} = (r - l, s - k, t - i),$$
 (5.5)

I. If $\tilde{u} = (i, k, l)$ is defined as a triangular fuzzy set, and $\tilde{v} = (r, s, l)$ is assumed a nonnegative triangular fuzzy set, then

$$\widetilde{u}^{*}\widetilde{v} = \begin{cases}
(i * r, k * s, l * t) & \text{if } i \geq 0, \\
(i * t, k * s, l * t) & \text{if } i \leq 0, l \geq 0, \\
(i * t, k * s, l * r) & \text{if } l \leq 0,
\end{cases}$$
(5.6)

Definition 5.4. it can be assumed that $\tilde{u} \leq \tilde{v}$, if and only if:

i. k < s, or

ii.
$$k = s$$
, and $(l - i) > (t - r)$ or (5.7)

iii. k = s, (l - i) = (t - r) and (i + l) < (r + t)

5.4. FFP model in closed-loop supply chain

Fuzzy programming is a prominent technique in optimization. Although all parameters and variables are assumed to be precise in general mathematical models, there is often imprecise information in real life particularly in CLSCs. Therefore, fuzzy numbers and variables should be

applied in modeling CLSCs. It is aimed to develop and apply a solution approach according to the algorithm proposed by Ezzati et al., (2015), to solve the FFP model in the introduced CLSC. Problem 5.8 is considered as the typical arrangement of FFP.

Max (Min)
$$\widetilde{C}^{T} \widetilde{X}$$
 (5.8)
s.t. $\widetilde{A} \widetilde{X} = \widetilde{b}$
Where $\widetilde{C}^{T} = [\widetilde{C}_{j}]_{l*n}$, $\widetilde{X} = [\widetilde{X}_{j}]_{n*l}$, $\widetilde{A} = [\widetilde{a}_{ij}]_{m*n}$, $\widetilde{b} = [\widetilde{b}_{i}]_{m*l}$, $i = 1, 2, ..., m$ and $j = 1, 2, ..., n$, $\widetilde{C}^{T} \widetilde{X}$
 $= ((\widetilde{C}^{T} X)^{l}, (\widetilde{C}^{T} X)^{c}, (\widetilde{C}^{T} X)^{u}), \widetilde{A} \widetilde{X} = ((\widetilde{A} X)^{l}, (\widetilde{A} X)^{c}, (\widetilde{A} X)^{u}), \widetilde{b} = ((b)^{l}, (b)^{c}, (b)^{u}), \widetilde{X} = ((X)^{l}, (X)^{c}, (X)^{u}),$
 $(X)^{l} \ge 0$, therefore Problem (5.8) is indicated as follows:

Max (Min)
$$((\acute{C}^{T} X)^{l}, (\acute{C}^{T} X)^{c}, (\acute{C}^{T} X)^{u})$$
 (5.9)
s.t. $((\acute{A} X)^{l}, (\acute{A} X)^{c}, (\acute{A} X)^{u}) = ((b)^{l}, (b)^{c}, (b)^{u})$

The steps to find the solution of the problem are mentioned in this section.

Step 1: To solve Problem (5.9), the problem is written as follows:

$$\begin{aligned} &\text{Max (Min) } ((\acute{C}^{T} X)^{l}, (\acute{C}^{T} X)^{c}, (\acute{C}^{T} X)^{u}) \end{aligned} \tag{5.10} \\ &s.t. \ (\acute{A} X)^{l} = (b)^{l}, (\acute{A} X)^{c} = (b)^{c}, (\acute{A} X)^{u} = (b)^{u} \\ &(X)^{c} - (X)^{l} \ge 0, (X)^{u} - (X)^{c} \ge 0, (X)^{l} \ge 0 \end{aligned}$$

Step 2: Problem (5.10) is divided to the three following crisp objectives:

Max (Min)
$$(\dot{C}^{T}\dot{X})^{c}$$
, (5.11)
Min (Max) $((\dot{C}^{T}\dot{X})^{u} - (\dot{C}^{T}\dot{X})^{l})$
Max (Min) $((\dot{C}^{T}\dot{X})^{l} + (\dot{C}^{T}\dot{X})^{u})$,
s.t. $(\dot{A}\dot{X})^{l} = (b)^{l}$, $(\dot{A}\dot{X})^{c} = (b)^{c}$, $(\dot{A}\dot{X})^{u} = (b)^{u}$
 $(\dot{X})^{c} - (\dot{X})^{l} \ge 0$, $(\dot{X})^{u} - (\dot{X})^{c} \ge 0$, $(\dot{X})^{l} \ge 0$

Step 3: In this step, the first objective function of Problem (5.11) is considered regarding to the defined constraints.

Max (Min)
$$(\acute{C}^{T} X)^{c}$$
, (5.12)
s.t. $(\acute{A} X)^{l} = (b)^{l}$, $(\acute{A} X)^{c} = (b)^{c}$, $(\acute{A} X)^{u} = (b)^{u}$
 $(X)^{c} - (X)^{l} \ge 0$, $(X)^{u} - (X)^{c} \ge 0$, $(X)^{l} \ge 0$

Thereafter, if a unique optimal solution was obtained explicitly for $\tilde{X}^* = ((X^*)^l, (X^*)^c, (X^*)^u)$ in Step 3, we stop; otherwise we go to the next step. $(\tilde{X}^* = (X^*)^l, (X^*)^c, (X^*)^u)$ is considered as a unique optimal solution, if the following conditions are fulfilled:

- (i) $\widetilde{X}^* = [\widetilde{X}_j^*]_{n*l}$, where $\widetilde{X}_j^* \in TF(\mathbb{R})^+ j = 1, 2, ..., n$,
- (ii) $\acute{A}X^* = b$,

(iii)
$$\forall \widetilde{X} = ((X)^l, (X)^c, (X)^u) \in \widetilde{S} = \{\widetilde{X} \mid \widetilde{A}\widetilde{X} = \widetilde{b}, \ \widetilde{X} = [\widetilde{X}_j]_{n*l} \text{ where } \widetilde{X}_j \in TF(\mathbb{R})^+\}, \ \widetilde{C}^T \widetilde{X} \leq \widetilde{C}^T \widetilde{X}^*$$

(in case of minimization $\widetilde{C}^T \widetilde{X} \geq \widetilde{C}^T \widetilde{X}^*$).

Step 4: Problem (5.13) is solved regarding the solution (p^*) obtained in Step 3. If the unique optimal solution is obtained for $\tilde{X}^* = ((X^*)^l, (X^*)^c, (X^*)^u)$, we stop, otherwise we go to Step 5.

$$\begin{array}{l}
\text{Min (Max) } ((\dot{C}^{T} \dot{X})^{u} - (\dot{C}^{T} \dot{X})^{l}) \\
\text{s.t. } (\dot{C}^{T} \dot{X})^{c} &= p^{*} \\
(\dot{A} \dot{X})^{l} &= (b)^{l}, \ (\dot{A} \dot{X})^{c} &= (b)^{c}, \ (\dot{A} \dot{X})^{u} = (b)^{u} \\
(\dot{X})^{c} - (\dot{X})^{l} \geq 0, \ (\dot{X})^{u} - (\dot{X})^{c} \geq 0, \ (\dot{X})^{l} \geq 0
\end{array}$$
(5.13)

Step 5: Problem (5.14) is solved according to the solutions (p^* and q^*) obtained in Steps 3 and 4.

$$Max (Min) ((\dot{C}^{T} X)^{l} + (\dot{C}^{T} X)^{u}),$$

$$s.t. ((\dot{C}^{T} X)^{u} - (\dot{C}^{T} X)^{l}) = q^{*}$$

$$(\dot{C}^{T} X)^{c} = p^{*}$$

$$(\dot{A} X)^{l} = (b)^{l}, (\dot{A} X)^{c} = (b)^{c}, (\dot{A} X)^{u} = (b)^{u}$$

$$(X)^{c} - (X)^{l} \ge 0, (X)^{u} - (X)^{c} \ge 0, (X)^{l} \ge 0$$

$$(5.14)$$

$$(5.14)$$

As indicated by the algorithm, it is supposed to define the lower, middle, and upper ranges for the objective at the beginning of the solution approach. Since the objective function of the introduced algorithm included vector X in the same direction, all lower, middle, and upper ranges were defined based on Eq. (5.9) $(z^l = (\dot{C}^T X)^l, z^c = (\dot{C}^T X)^c, z^u = (\dot{C}^T X)^u)$. However, in the proposed FFP model, the objective function consists of two parts; the first part is about the revenue of selling products, and the second part is about all imposed costs associated with production, transportation, disposal, and inventory costs (as the variable costs), and costs of opening the plants, retailers, and battery recovery centers (as the fixed costs). Therefore, the upper range of the objective can be obtained when all parameters and decision variables contributing to achieve the revenue are in the upper range, and all parameters and decision variables causing imposed cost are in the lower range. By the reverse approach, the lower range of the objective can be reached. To define the middle range, the same instruction with regard to Eq. (5.9) ($z^c = (\hat{C}^T X)^c$) is followed up. Therefore, our proposed FFP model for the battery CLSC network can be written as Eqs. (5.15) - (5.67). Then, the solution will be calculated based on the defined steps.

$$\begin{aligned} & \left\{ z^{l} = \sum_{r} \sum_{k} \sum_{j} \sum_{i} (\delta_{j}^{l} - H_{j}^{u} E_{rk}) S_{rkjt}^{l} - (\sum_{s} \sum_{i} \sum_{\eta} \sum_{\eta} (N_{s\eta}^{u} + F_{\eta}^{u} E_{si}) Q_{si\eta t}^{u} + \sum_{i} \sum_{j} \sum_{r} \sum_{i} (P_{j}^{u} + G_{j}^{u} E_{ir}) R_{iijt}^{u} \right. \\ & \left. + \sum_{r} \sum_{j} \sum_{i} \alpha_{j}^{u} I_{rjt}^{u} + \sum_{k} \sum_{l} \sum_{j} \sum_{i} M_{j}^{u} E_{kl} T_{kljt}^{u} + \sum_{l} \sum_{i} \sum_{\eta} \sum_{i} (-a_{\eta}^{l} + O_{\eta}^{u} E_{li}) U_{li\eta t}^{l} + \sum_{l} \sum_{\eta} \sum_{r} (f_{\eta}^{u} + \theta_{\eta}^{u} E_{l}) \lambda_{l\eta t}^{u} \right. \\ & \left. + \sum_{s} A_{s}^{u} Y_{s} + \sum_{i} B_{i}^{u} V_{i} + \sum_{r} R_{r}^{u} W_{r} + \sum_{l} C_{l}^{u} X_{l} \right) \right. \\ & \left\{ z^{c} = \sum_{r} \sum_{k} \sum_{j} \sum_{i} (\delta_{j}^{c} - H_{j}^{c} E_{rk}) S_{rkjt}^{c} - (\sum_{s} \sum_{i} \sum_{\eta} \sum_{\eta} (N_{s\eta}^{c} + F_{\eta}^{c} E_{si}) Q_{si\eta t}^{c} + \sum_{i} \sum_{r} \sum_{j} \sum_{t} (P_{j}^{c} + G_{j}^{c} E_{ir}) R_{irjt}^{c} \right. \\ & \left. + \sum_{r} \sum_{j} \sum_{t} \alpha_{j}^{c} I_{rjt}^{c} + \sum_{k} \sum_{l} \sum_{j} \sum_{i} M_{j}^{c} E_{kl} T_{kljt}^{c} + \sum_{l} \sum_{i} \sum_{\eta} \sum_{\tau} (-a_{\eta}^{c} + O_{\eta}^{c} E_{li}) U_{li\eta t}^{c} + \sum_{l} \sum_{\eta} \sum_{\tau} (f_{\eta}^{c} + \theta_{\eta}^{c} E_{l}) \lambda_{l\eta t}^{c} \right. \\ & \left. + \sum_{s} \sum_{i} \sum_{j} \sum_{t} \alpha_{j}^{c} I_{rjt}^{i} + \sum_{k} \sum_{l} \sum_{j} \sum_{i} M_{j}^{c} E_{kl} T_{kljt}^{c} + \sum_{l} \sum_{i} \sum_{\eta} \sum_{\tau} (-a_{\eta}^{c} + O_{\eta}^{c} E_{li}) U_{li\eta t}^{c} + \sum_{l} \sum_{\eta} \sum_{\tau} (P_{j}^{l} + G_{j}^{l} E_{ir}) \lambda_{l\eta t}^{c} \right. \\ & \left. + \sum_{s} \sum_{i} \sum_{j} \sum_{t} \alpha_{j}^{c} I_{rjt}^{i} + \sum_{k} \sum_{l} \sum_{j} \sum_{i} M_{j}^{l} E_{kl} T_{kljt}^{l} + \sum_{i} \sum_{\eta} \sum_{\tau} (N_{s\eta}^{l} + F_{\eta}^{l} E_{si}) Q_{si\eta t}^{l} + \sum_{i} \sum_{j} \sum_{r} \sum_{i} (P_{j}^{l} + G_{j}^{l} E_{ir}) \lambda_{l\eta t}^{l} \right. \\ & \left. + \sum_{s} \sum_{i} \sum_{j} \sum_{t} \alpha_{j}^{c} I_{rjt}^{l} + \sum_{k} \sum_{l} \sum_{j} \sum_{i} M_{j}^{l} E_{kl} T_{kljt}^{l} + \sum_{i} \sum_{\eta} \sum_{\tau} \sum_{i} (-a_{\eta}^{u} + O_{\eta}^{l} E_{li}) U_{ii\eta t}^{u} + \sum_{l} \sum_{\eta} \sum_{\tau} (f_{\eta}^{l} + \theta_{\eta}^{l} E_{l}) \lambda_{l\eta t}^{l} \right. \\ \\ & \left. + \sum_{s} A_{s}^{l} Y_{s} + \sum_{i} B_{i}^{l} V_{i} + \sum_{r} R_{r}^{l} W_{r} + \sum_{l} C_{l}^{l} X_{l} \right)$$

s.t.

$$I_{rjt}^{l} = I_{rjt-1}^{l} + \sum_{i} R_{irjt}^{l} - \sum_{k} S_{rkjt}^{l} \qquad \forall r, j, t$$
(5.16)

$$I_{rjt}^{c} = I_{rjt-I}^{c} + \sum_{i} R_{irjt}^{c} - \sum_{k} S_{rkjt}^{c} \qquad \forall r, j, t$$
(5.17)

$$I_{rjt}^{u} = I_{rjt-I}^{u} + \sum_{i} R_{irjt}^{u} - \sum_{k} S_{rkjt}^{u} \qquad \forall r, j, t$$
(5.18)

$$\sum_{s} Q_{sint}^{l} + \sum_{l} U_{lint}^{l} = \sum_{r} \sum_{j} \left(R_{irjt}^{l} \right) v_{jn} \qquad \forall i, \eta, t$$
(5.19)

$$\sum_{s} Q_{si\eta t}^{c} + \sum_{l} U_{li\eta t}^{c} = \sum_{r} \sum_{j} \left(R_{irjt}^{c} \right) v_{jn} \qquad \forall i, \eta, t$$
(5.20)

$$\sum_{s} \mathcal{Q}_{si\eta t}^{u} + \sum_{l} U_{li\eta t}^{u} = \sum_{r} \sum_{j} \left(R_{irjt}^{u} \right) v_{jn} \qquad \forall i, \eta, t$$
(5.21)

$$\sum_{i} R_{irjt}^{l} + I_{rjt}^{l} \ge \sum_{k} S_{rkjt}^{l} \qquad \forall r, j, t$$
(5.22)

$$\sum_{i} R_{irjt}^{c} + I_{rjt}^{c} \ge \sum_{k} S_{rkjt}^{c} \qquad \forall r, j, t$$
(5.23)

$$\sum_{i} R^{u}_{irjt} + I^{u}_{rjt} \ge \sum_{k} S^{u}_{rkjt} \qquad \forall r, j, t$$
(5.24)

$$\sum_{r} S_{rkjt}^{l} \le d_{kjt}^{l} \qquad \forall k, j, t \qquad (5.25)$$

$$\sum_{r} S_{rkjt}^{c} \le d_{kjt}^{c} \qquad \forall k, j, t \qquad (5.26)$$

$$\sum_{r} S^{u}_{rkjt} \le d^{u}_{kjt} \qquad \forall k, j, t$$
(5.27)

$$\sum_{r} S_{rkjt}^{l} \ge \sum_{l} T_{kljt}^{l} \qquad \forall k, j, t$$
(5.28)

$$\sum_{r} S_{rkjt}^{c} \ge \sum_{l} T_{kljt}^{c} \qquad \forall k, j, t \qquad (5.29)$$

$$\sum_{r} S^{u}_{rkjt} \ge \sum_{l} T^{u}_{kljt} \qquad \forall k, j, t$$
(5.30)

$$\sum_{l} T_{kljt}^{l} = z_{kjt}^{l} \qquad \forall k, j, t \qquad (5.31)$$

$$\sum_{l} T_{kljt}^{c} = z_{kjt}^{c} \qquad \forall k, j, t \qquad (5.32)$$

$$\sum_{l} T^{u}_{kljt} = z^{u}_{kjt} \qquad \forall k, j, t$$
(5.33)

$$\varepsilon_{\eta}^{l} \sum_{k} \sum_{j} \left(T_{kljt}^{l} \right) v_{j\eta} \leq \lambda_{l\eta t}^{l} \qquad \qquad \forall l, \eta, t \qquad (5.34)$$

$$\varepsilon_{\eta}^{c} \sum_{k} \sum_{j} \left(T_{kljt}^{c} \right) v_{j\eta} \leq \lambda_{l\eta t}^{c} \qquad \forall l, \eta, t \qquad (5.35)$$

$$\varepsilon_{\eta}^{u} \sum_{k} \sum_{j} \left(T_{kljt}^{u} \right) v_{j\eta} \leq \lambda_{l\eta t}^{u} \qquad \qquad \forall l, \eta, t \qquad (5.36)$$

$$\sum_{k} \sum_{j} \left(T_{kljt}^{l} \right) v_{j\eta} = \sum_{i} U_{li\eta t}^{l} + \lambda_{l\eta t}^{l} \qquad \forall l, \eta, t$$
(5.37)

$$\sum_{k} \sum_{j} \left(T_{kljt}^{c} \right) v_{j\eta} = \sum_{i} U_{li\eta t}^{c} + \lambda_{l\eta t}^{c} \qquad \forall l, \eta, t$$
(5.38)

$$\sum_{k} \sum_{j} \left(T_{kljt}^{u} \right) v_{j\eta} = \sum_{i} U_{li\eta t}^{u} + \lambda_{l\eta t}^{u} \qquad \forall l, \eta, t$$
(5.39)

$$\sum_{s} \sum_{\eta} Q_{si\eta t}^{l} + \sum_{l} \sum_{\eta} U_{li\eta t}^{l} \leq V_{i} \sum_{\eta} g_{i\eta} \qquad \forall i, t$$
(5.40)

$$\sum_{s} \sum_{\eta} Q_{si\eta t}^{c} + \sum_{l} \sum_{\eta} U_{li\eta t}^{c} \leq V_{i} \sum_{\eta} g_{i\eta} \qquad \forall i, t$$
(5.41)

$$\sum_{s} \sum_{\eta} Q_{si\eta t}^{u} + \sum_{l} \sum_{\eta} U_{li\eta t}^{u} \leq V_{i} \sum_{\eta} g_{i\eta} \qquad \forall i, t \qquad (5.42)$$

$$\sum_{i} \sum_{j} R_{irjt}^{l} + \sum_{j} I_{rjt}^{l} \le W_{r} \sum_{j} h_{rj} \qquad \forall r, t \qquad (5.43)$$

$$\sum_{i} \sum_{j} R_{irjt}^{c} + \sum_{j} I_{rjt}^{c} \le W_r \sum_{j} h_{rj} \qquad \forall r, t \qquad (5.44)$$

$$\sum_{i} \sum_{j} R^{u}_{irjt} + \sum_{j} I^{u}_{rjt} \le W_r \sum_{j} h_{rj} \qquad \forall r, t \qquad (5.45)$$

$$\sum_{k} \sum_{j} T_{kljt}^{l} \leq X_{l} \sum_{j} n_{lj} \qquad \forall l, t \qquad (5.46)$$

$$\sum_{k} \sum_{j} T_{kljt}^{c} \leq X_{l} \sum_{j} n_{lj} \qquad \qquad \forall l, t \qquad (5.47)$$

$$\sum_{k} \sum_{j} T_{kljt}^{u} \leq X_{l} \sum_{j} n_{lj} \qquad \forall l, t \qquad (5.48)$$

$$\sum_{i} \sum_{\eta} Q_{si\eta t}^{l} \leq Y_{s} \sum_{\eta} u_{s\eta} \qquad \qquad \forall s, t \qquad (5.49)$$

$$\sum_{i} \sum_{\eta} Q_{si\eta t}^{c} \leq Y_{s} \sum_{\eta} u_{s\eta} \qquad \qquad \forall s, t \qquad (5.50)$$

$$\sum_{i} \sum_{\eta} Q_{si\eta t}^{u} \le Y_{s} \sum_{\eta} u_{s\eta} \qquad \qquad \forall s, t \qquad (5.51)$$

 $Q_{si\eta t}^{c} - Q_{si\eta t}^{l} \ge 0 \qquad \forall s, i, \eta, t$ (5.52)

 $Q_{si\eta t}^{u} - Q_{si\eta t}^{c} \ge 0 \qquad \qquad \forall s, i, \eta, t \qquad (5.53)$

$$R_{irjt}^c - R_{irjt}^l \ge 0 \qquad \qquad \forall i, r, j, t \qquad (5.54)$$

$$\begin{aligned} R_{irji}^{n} - R_{irji}^{n} &\geq 0 & \forall i, r, j, t & (5.55) \\ S_{rkjt}^{n} - S_{rkjt}^{l} &\geq 0 & \forall r, k, j, t & (5.56) \\ S_{rkjt}^{n} - S_{rkjt}^{n} &\geq 0 & \forall r, k, j, t & (5.57) \\ T_{kljt}^{n} - T_{kljt}^{l} &\geq 0 & \forall k, l, j, t & (5.58) \\ T_{kljt}^{n} - T_{kljt}^{n} &\geq 0 & \forall k, l, j, t & (5.59) \\ U_{irjt}^{n} - U_{irjt}^{l} &\geq 0 & \forall l, i, \eta, t & (5.60) \\ U_{irjt}^{n} - U_{irjt}^{l} &\geq 0 & \forall l, i, \eta, t & (5.61) \\ I_{rjt}^{n} - I_{rjt}^{l} &\geq 0 & \forall r, j, t & (5.62) \\ I_{rjt}^{n} - I_{rjt}^{l} &\geq 0 & \forall l, \eta, t & (5.63) \\ \lambda_{irjt}^{n} - \lambda_{irjt}^{l} &\geq 0 & \forall l, \eta, t & (5.64) \\ \lambda_{irjt}^{n} - \lambda_{irjt}^{l} &\geq 0 & \forall l, \eta, t & (5.65) \\ V_{i}, W_{r}, X_{i}, Y_{s} &\in \{0, 1\} & \forall l, r, l, s & (5.66) \end{aligned}$$

$Q_{si\eta t}^{l}, R_{irjt}^{l}, S_{rkjt}^{l}, T_{kljt}^{l}, U_{li\eta t}^{l}, \lambda_{l\eta t}^{l}, I_{rjt}^{l} \ge 0 \qquad \forall s, i, \eta, t, r, j, k, l$ (5.67)

5.5. Values of the parameters and solution

As mentioned in Chapter 3, the model has been designed for a battery CLSC network in Vancouver, Canada. The middle triangular fuzzy values for all parameters are assumed to be equal to the parameters values of the deterministic model, while the lower and upper triangular fuzzy values of parameters are assumed to be equal to the lower and upper ranges of each value. For further elaboration, the lower retail price of fuel was 1.06 in Vancouver during the last year. According to the fuel consumption guide, each truck almost needs 8.15 litre per 100 kilometers. Therefore, the lower range transportation cost is approximately estimated by (8.15/100)*1.06 =

0.087. The values of the fuzzy parameters applied to solve the proposed FFP model are provided in Table 5.1.

Table 5.1		
Values of	some parameters applied to solve the proposed FF	P model
J = 3	$\widetilde{A}_s = (900, 1,000, 1,100)$	$\widetilde{P}_{j} = (14, 15, 16)$
N = 5	$\widetilde{B}_i = (900,000, 1,000,000, 1,100,000)$	\tilde{f}_{η} = (0.9, 1, 1.1)
<i>S</i> = 5	$\widetilde{R}_r = (1,400, 1,500, 1,600)$	$\tilde{a}_{\eta} = (9, 10, 11)$
I = 6	$\widetilde{C}_l = (1,400, 1,500, 1,600)$	$g_{i\eta} = (2,500,000)_{6*5}$
R = 7	$\tilde{\delta}_j = (145, 150, 155)$	$h_{rj} = (10,000)_{7*3}$
<i>K</i> = 22	$\widetilde{G}_{j} = \widetilde{H}_{j} = \widetilde{M}_{j} = (0.087, 0.097, 0.107)$	$n_{lj} = (10,000)_{10*3}$
L = 10	$\widetilde{F}_{\eta} = \widetilde{O}_{\eta} = \widetilde{\theta}_{\eta} = (0.0174, 0.0194, 0.0214)$	$u_{s\eta} = (30,000)_{5*5}$
T = 3	$\tilde{\epsilon}_{\eta} = (0.09, 0.10, 0.11)$	$\tilde{\alpha}_j = (38, 40, 42)$

IBM ILOG CPLEX 12.7.1.0 is used for solving the mathematical model based on the defined steps. In the last step, the FFP model is solved in 32 seconds. 10,469 constraints, 10,680 single variables, 28 binary variables, and 107,415 non-zero coefficients exist. The results of FFP model are illustrated in Table 5.2.

5.6. Comparison between the solution of deterministic and FFP model

In order to compare the solutions obtained from deterministic and FFP model, the values parameters using in these methods should be considered at first. In FFP model, TFNs were employed to define each parameter, and solution was calculated for lower value (pessimistic approach), middle value (most likely approach), and upper value (optimistic approach). It is supposed to be notified that the value of binary variables estimated by both methods were exactly equal. Existence of lower and upper optimal value for objective function and decision variables are the privilege of FFP compared to deterministic model.

The configuration of CLSC is usually applied to make strategic decision which is impossible to change in a short time. Therefore, all possible range of parameters, decision variables, and objective function should be considered for making a comprehensive decision. The FFP was applied to find the range of possible results for objective function and decision variables in uncertain situation.

Table 5.2 Solution of the FFP model

	Ι	Lower value		Middle value		Upper value	Binary variables (Y_s , V_i , W_r , X_l)
Objective	1:	5,865,536.69		19,031,814.21	2	0,751,305.19	Supplier Location (Y_s) :
$\widetilde{Q}_{si\eta t}$	206,466.82	Period 1: 0	206,466.82	Period 1: 0	206,466.82	Period 1: 0	Y_1 (Downtown), Y_5
		Period 2: 206,466.82		Period 2: 206,466.82		Period 2: 206,466.82	(Downtown)
\widetilde{R}_{irjt}	52,022.81	Period 1: 5,364.72	57,655.90	Period 1: 8,181.27	57,655.90	Period 1: 8,181.27	Plant Location (V_i): V_2
Tenji		Period 2: 46,658.09		Period 2: 49,474.635		Period 2: 49,474.635	(Downtown)
<i>S</i> _{rkjt}	172,872.74	Period 1: 85,404.74	181,536	Period 1: 90,768	181,536	Period 1: 90,768	Retailer Location (W_r) :
<i>Ğт</i> кji	172,072.71	Period 2: 87,468	101,550	Period 2: 90,768	101,550	Period 2: 90,768	W_1 (Strathcona) W_2
\tilde{T}_{kljt}	11,790.60	Period 1: 5,895.3	18,180.60	Period 1: 9,090.3	24,780.60	Period 1: 12,390.3	(Strathcona), W_3 (Grandview Woodland),
I kijt	11,790.00	Period 2: 5,895.3	10,100.00	Period 2: 9,090.3	24,700.00	Period 2: 12,390.3	W_4 (Grandview
$\widetilde{U}_{li\eta t}$	53,647.23	Period 1: 26,823.62	81,812.70	Period 1: 40,906.35	81,812.70	Period 1: 40,906.35	Woodland), W_7
Cum	55,017.25	Period 2: 26,823.62	01,012.70	Period 2: 40,906.35	01,012.70	Period 2: 40,906.35	(Downtown)
Ĩ _{rjt}		Period 0: 162,143.30		Period 0: 165,173.46		Period 0: 165,173.46	Battery recovery center
1 rjt	285,539.9	Period 1: 82,103.28	289,053.55	Period 1: 82,586.73	289,053.55	Period 1: 82,586.73	location (X_l) : X_3
		Period 2: 41,293.37		Period 2: 41,293.365		Period 2: 41,293.365	(Strathcona), X_5
$\widetilde{\lambda}_{l\eta t}$	5,305.77	Period 1: 2,652.88	9,090.3	Period 1: 4,545.15	42,090.3	Period 1: 21,045.15	- (Renfrew- Collinwood)
$n_{l\eta t}$	5,505.11	Period 2: 2,652.88	,070.5	Period 2: 4,545.15		Period 2: 21,045.15	

5.7. Application of FFP with regard to scenario-based analysis to address uncertainty

In FFP method, it is intended to find lower range, middle range, and upper range for the objective function with regard to lower range, middle range, and upper range of parameters and non-negative variables. However, this question may arise for decision makers; what if there is more than one alternative for lower range, middle range, and upper range for one of the parameters such as demand or return. In this case, scenario-based analysis can be employed to consider different cases for each lower range, or middle range, or upper range of demand and return. The proposed FFP model for battery CLSC network with regard to different scenarios can be written as follows:

$$\begin{cases} z^{l} = \sum_{\omega} \sum_{r} \sum_{k} \sum_{j} \sum_{t} \Phi_{\omega} (\delta_{j}^{l} - H_{j}^{u} E_{rk}) S_{rkjt\omega}^{l} - (\sum_{\omega} \sum_{s} \sum_{i} \sum_{\eta} \sum_{r} \Phi_{\omega} (N_{s\eta}^{u} + F_{\eta}^{u} E_{si}) Q_{sint\omega}^{u} + \sum_{s} \sum_{i} \sum_{j} \sum_{q} \Phi_{\omega} \alpha_{j}^{r} I_{rij\omega}^{u} + \sum_{\omega} \sum_{k} \sum_{i} \sum_{j} \sum_{r} \Phi_{\omega} (M_{j}^{u} E_{kl} T_{kljt\omega}^{u} + \sum_{s} \sum_{i} \sum_{j} \Phi_{\omega} (I_{\eta}^{u} + I_{\eta}^{u} E_{ij}) Q_{int\omega}^{u} + \sum_{s} \sum_{i} \sum_{q} \sum_{r} \Phi_{\omega} (f_{\eta}^{u} + I_{\eta}^{u} E_{ij}) Z_{int\omega}^{u} + \sum_{s} \sum_{i} \sum_{q} \sum_{r} \Phi_{\omega} (I_{\eta}^{u} + I_{\eta}^{u} E_{ij}) Z_{int\omega}^{u} + \sum_{s} \sum_{i} \sum_{q} \sum_{r} \Phi_{\omega} (I_{\eta}^{c} + I_{\eta}^{u} E_{ij}) Z_{int\omega}^{u} + \sum_{s} \sum_{i} \sum_{q} \sum_{r} \Phi_{\omega} (I_{\eta}^{c} + I_{\eta}^{c} E_{ij}) Z_{int\omega}^{c} + \sum_{s} \sum_{i} \sum_{q} \sum_{r} \Phi_{\omega} (I_{\eta}^{c} + I_{\eta}^{c} E_{ij}) Z_{int\omega}^{c} + \sum_{s} \sum_{i} \sum_{q} \sum_{r} \Phi_{\omega} (I_{\eta}^{c} + I_{\eta}^{c} E_{ij}) Z_{int\omega}^{c} + \sum_{s} \sum_{i} \sum_{q} \sum_{r} \Phi_{\omega} (I_{\eta}^{c} + I_{\eta}^{c} E_{ij}) U_{intw}^{c} + \sum_{w} \sum_{r} \sum_{i} \sum_{q} \Phi_{w} (I_{\eta}^{c} + I_{\eta}^{c} E_{ij}) U_{intw}^{c} + \sum_{w} \sum_{r} \sum_{i} \sum_{q} \Phi_{w} (I_{\eta}^{c} + I_{\eta}^{c} E_{ij}) U_{intw}^{c} + \sum_{w} \sum_{r} \sum_{i} \sum_{q} \Phi_{w} (I_{\eta}^{c} + I_{\eta}^{c} E_{ij}) U_{intw}^{c} + \sum_{w} \sum_{r} \sum_{i} \sum_{q} \Phi_{w} (I_{\eta}^{c} + I_{\eta}^{c} E_{ij}) U_{intw}^{c} + \sum_{w} \sum_{i} \sum_{q} \sum_{i} \Phi_{w} (I_{\eta}^{c} + I_{\eta}^{c} E_{ij}) U_{intw}^{c} + \sum_{w} \sum_{i} \sum_{q} \sum_{i} \sum_{q} \Phi_{w} (I_{\eta}^{c} + I_{\eta}^{c} E_{ij}) Z_{intw}^{c} + \sum_{s} \sum_{s} \sum_{i} \sum_{q} \sum_{i} \Phi_{w} (I_{\eta}^{c} + I_{\eta}^{c} E_{ij}) U_{intw}^{c} + \sum_{w} \sum_{i} \sum_{q} \sum_{i} \sum_{q} \Phi_{w} (I_{\eta}^{c} + I_{\eta}^{c} E_{ij}) Z_{intw}^{c} + \sum_{i} \sum_{k} \sum_{i} \sum_{q} \sum_{i} \sum_{q} \sum_{i} \sum_{q} \Phi_{w} (I_{q}^{c} + I_{q}^{c} E_{ij}) Z_{intw}^{c} + \sum_{i} \sum_{i} \sum_{q} \sum_{i} \sum_{q} \sum_{i} \Phi_{w} (I_{q}^{c} + I_{q}^{c} E_{ij}) Z_{intw}^{c} + \sum_{i} \sum_{i} \sum_{q} \sum_{i} \sum_{q} \Phi_{w} (I_{q}^{c} + I_{q}^{c} E_{ij}) Z_{intw}^{c} + \sum_{i} \sum_{i} \sum_{q} \sum_{i} \Phi_{w} (I_{q}^{c} + I_{q}^{c} E_{ij}) Z_{intw}^{c} + \sum_{i} \sum_{i} \sum_{q} \sum_{i} \Phi_{w} (I_{q}^{c} + I_{q}^{c} E_{ij}) Z_{intw}^{c} + \sum_{i} \sum_{i} \sum_{q} \sum_{i} \Phi_{w} (I_{q}^{c} + I_{q}^{c} E_{ij}) Z_{intw}^{c} + \sum_{i} \sum_{i} \sum_$$

s.t.

Eqs. (5.16) – (5.67)

Scenario-based analysis is performed to consider the impacts of different possible alternatives of uncertain demand and return on the total expected profit. It is assumed that the value of market's demand and returned product in Scenario 3 is defined similarly to the proposed FFP

model. Each scenario is indicated the 0.5 percent alteration in demand or return. As a matter of fact, all possible combinations of 0.5 percent changes in market's demand and returned product are examined. As indicated by Table 5.3, the values of objective functions are compared with Scenario 3 (e.g. change% in Scenario 1 for middle range total expected profit: (19,118,799.79-19,031,814.217)/19,031,814.217=0.4571%). Furthermore, the FFP with regard to scenario-based model (comprising of 52,324 constraints, 53,388 non-negative variables, 28 binary variables) is applied and the results are indicated in Table 5.3 as well. The scenario-based model is assumed to include all possible 5 scenarios with probability of (0.15, 0.2, 0.3, 0.2, 0.15). The total expected profit of FFP with regard to scenario-based analysis have been depicted in Fig. 5.2.

Table 5.3

Scenarios	Demand	Return	Lower total	Middle total	Upper total	change %
	change%	change%	expected profit	expected profit	expected profit	(Middle range)
1	0.5% increase	0.5% decrease	15,944,815.99	19,118,799.79	20,846,087.70	0.4571%
2	0.5% decrease	0.5% increase	15,786,142.04	18,944,828.64	20,656,522.63	-0.4571%
3 (base-case)	No change	No change	15,865,479.04	19,031,814.21	20,751,305.19	0
4	0.5% increase	0.5% increase	16,200,565.09	19,131,543.40	20,859,178.07	0.5240%
5	0.5% decrease	0.5% decrease	15,780,691.62	18,931784.48	20,643,162.71	-0.5256%
6 (scenario-	Combination of	five scenarios	15,865,758.57	19,032,452.08	20,751,955.06	0.0034%
based)						

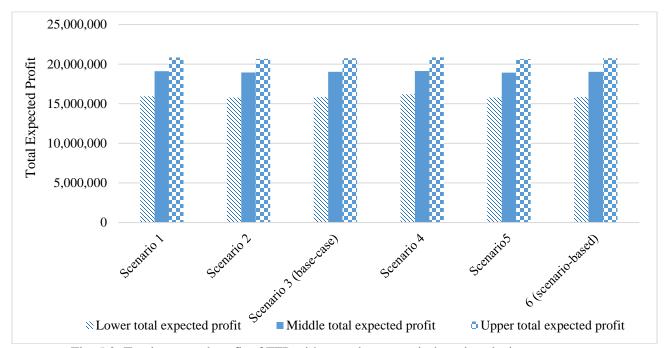


Fig. 5.2. Total expected profit of FFP with regard to scenario-based analysis

5.8. An extension to multi-objective

Since the proposed FFP model has been defined for the battery CLSC network, it is commonsensical to maximize the green factors as well. To this aim, two qualitative parameters are considered including $M'_{i\eta}$ and $N'_{l\eta}$ as the measurement of the green factors for the potential plants, and the recovery centers, respectively. In this stage, it is assumed that some potential plants and recovery centers exist, and it is intended to select the best ones. $M'_{i\eta}$ is defined as the parameter of green performance allocating to potential plant *i* to produce the products via assembling of η components. Besides, $N'_{l\eta}$ is shown as the parameter of green performance the performance allocating to the potential battery recovery center *l* to recycle η components via disassembling the products. The second objective function is defined as follows:

$$Max \ z_{2} = \sum_{i} \sum_{\eta} M'_{i\eta} \left(\sum_{s} \sum_{t} \widetilde{Q}_{si\eta t} + \sum_{l} \sum_{t} \widetilde{U}_{li\eta t} + \sum_{r} \sum_{j} \sum_{t} \left(\widetilde{R}_{irjt} \right) v_{j\eta} \right) + \sum_{l} \sum_{\eta} N'_{l\eta} \left(\sum_{s} \sum_{j} \sum_{t} \left(\widetilde{T}_{kljt} \right) v_{j\eta} + \sum_{i} \sum_{t} \widetilde{U}_{li\eta t} + \sum_{t} \widetilde{\lambda}_{l\eta t} \right)$$
(5.68)

 $M'_{i\eta}$ and $N'_{l\eta}$ are qualitative factors. According to Chapter 4, fuzzy ANP method was applied for determining the values of those parameters. On the other hand, the problem is multi-objective. Two methods (distance and \mathcal{E} -constraint methods) are developed and applied to solve the multi-objective problem.

5.9. Distance method and the solution

To reach a solution close to the ideal values, the distance method is utilized for the proposed multi-objective CLSC network. In this method, ideal solution is the best value which can be obtained for each function disregarding other functions. As illustrated by Eq. (5.69), w_i is used as the distance metric. In this chapter, there are two objective functions including the total expected profit and the green performance which are maximized. Therefore, the objective function for the proposed model can be written as Eq. (5.70).

$$z = \left(\sum_{i} w_{i}^{\tau} \left(\frac{z_{i} - z_{i}^{*}}{z_{i}^{*}}\right)^{\tau}\right)^{\frac{1}{\tau}} \qquad \forall i = 1, 2..., \infty$$

$$(5.69)$$

$$Max \ z = \left(w_1^r \left(\frac{z_1 - z_1^*}{z_1^*}\right)^r + w_2^r \left(\frac{z_2 - z_2^*}{z_2^*}\right)^r\right)^{\frac{1}{r}}$$
(5.70)

s.t. Eqs. (5.16) - (5.67)

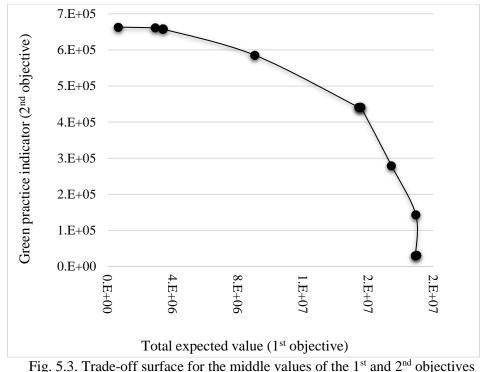
In this section, an algorithm based on Ezzati et al., (2015) is developed and applied to solve each fuzzy objective as discussed previously. The results are provided in Table 5.4. Then, the distance method is applied to find the solutions of the multi-objective model.

Table 5.4	
Optimal value of each fuzzy objective obtained separately subject to the defined constraints	

	Lower value	Middle value	Upper value
First objective	15,865,479.04	19,031,814.21	20,751,305.19
Second objective	657,201.28	682,630.48	686,392.48

To find the trade-off solution between the two mentioned fuzzy objectives, different pairs of w_i are utilized under the $\sum_{i} w_i = 1$ condition. The ideal solution for the lower range of the total expected profit and the lower range of green performance are 15,865,479.04 and 109,140, individually. Similarly, the distance method can explore one ideal solution of 20,751,000 and 133,410 for the upper range of the proposed multi-objective model. Table 5.5 illustrates the solutions for the middle values. As shown in Fig. 5.3, an ideal solution of one objective cannot be improved, unless the other objective value is sacrificed.

Table 5.5 Solutions for the 1st and 2nd objectives (middle values, distance method) W1 0 0.1 0.2 0.3 0.6 0.7 0.8 1 First 662,950 2,935,800 3,411,600 9,034,600 15,558,000 17,439,000 18,928,000 18,999,000 objective Second 663,190 661,190 657,790 585,650 441,380 279,160 143,350 30,666 objective



115. 5.5. Thus off surface for the initiale values of the 1 and 2 obj

5.10. E-constraint method and the solution

E-constraint can be employed to convert the multi-objective problem to a mono-objective optimization. It is aimed to apply E-constraint method to verify the answer of the proposed multi-objective FFP obtained from the distance method. In this technique, the objective with higher priority is chosen as the main objective function, and the other objective is assumed as a constraint. The converted problem can be written as:

 $Max \ z = z_1$ (5.71) s.t. $z_2 \ge \&$ Eqs. (5.16) - (5.67)

To achieve the trade-off solution through the \mathcal{E} -constraint method, different values of \mathcal{E} are considered. Hence, \mathcal{E} was employed from 50,000 to 109,140 for the lower range multi-objective problem. For every \mathcal{E} under 109,140, the value of the first objective was equal to 15,865,479.04, while the solution for \mathcal{E} upper than 109,140 became infeasible or unbounded. Similarly, converted FFP model was solved for \mathcal{E} between 50,000 to 133,410 for the upper range multi-objective, and the obtained objective was 20,751,305.19. However, the objective value of the

converted FFP for \mathcal{E} with higher than 133,410 became infeasible or unbounded for the upper range case. The middle values of the converted FFP are indicated in Table 5.6.

Table 5.6.

Solution	s of the prob	lem (middle	values, E-co	onstraint met	hod)			
3	663,190	661,190	657,790	585,650	441,380	279,160	143,350	30,666
Converted FFP	2,416,993.30	2,936,387.19	3,411,788.11	9,040,077.07	15,559,741.54	17,440,316.9	18,938,805.16	19,031,814.21

5.11. Conclusions

The proposed FFP model was applied for multi-echelon (multiple suppliers, plants, retailers, demand markets, battery recovery centers, and disposal center), multi-components, multi-products CLSC in multiple periods. The solution included the optimal range of objective function and decision variables with regard to period 1 and 2. In the proposed FFP model, each parameter was defined based on TFNs to cover all possible range of values. The advantage of FFP compared to other types of programming is assumption of fuzziness for decision variables. In nondeterministic programming, information is assumed to be imprecise. Therefore, existence of fuzzy decision variables led to have more flexibility for making strategic decision.

In order to extend possible alternatives, scenario-based analysis has been integrated with FFP method to consider different cases for each lower range, or middle range, or upper range of demand and return. The results indicated changes in demand have more impacts on total expected profit of battery CLSC in comparison with return. Furthermore, the FFP model has been developed to the multi-objective with the aim of considering green practices in plants and battery recovery centers. To solve the proposed multi-objective model, each fuzzy problem has been solved separately, then the distance method has been applied to address the multi-objective feature. In addition, \mathcal{E} -constraint method has been utilized for comparison the results with the distance method. According to the findings, distance and \mathcal{E} -constraint method indicated similar results for lower, middle, and upper ranges of the multi-objective FFP model.

CHAPTER 6. CONCLUSIONS AND FUTURE RESEARCH

6.1. Research contributions

The research contributions of this thesis were introduced as follows:

• Designing and examining CLSC network of battery in Vancouver with regard to the related organizations in Canada.

 Application of scenario-based analysis to develop the proposed model under the risk of unexpected changes in demand and return.

• Employing Fuzzy ANP to convert the qualitative factors as the measurement of the green performance of plants and battery recovery centers to the quantitative parameters.

• Application of FFP method to evaluate the impacts of uncertainty on CLSC network. Since, the configuration of battery CLSC may be applied for making strategic decision and it is impossible to change in a short-term, it is necessary to consider all possible optimal range of decision variables and objective function.

• Employing the combination of possibilistic (fuzzy) and scenario-based analysis to involve more one alternative for lower, middle, and upper range of demand and return.

• Utilization of distance technique and E-constraint method to determine the tradeoff surface of solution.

Assuming real distances in the proposed multi-echelon CLSC through Google
 Maps for estimating real transportation cost.

6.2. Conclusions

It was intended to develop a hybrid method to configure a battery CLSC network. The proposed model was extended to investigate the impact of uncertainty with respect to the environmental practices. Hence, some analyses were utilized and related solution approaches along with optimization models were developed.

A variety of concerns associated with manufacturing and remanufacturing of battery were described. As a matter of fact, discarded battery in landfills will become hazardous on account of spreading out the chemical materials into the soil and groundwater. Furthermore, some regulations urge the decision makers to emphasize the battery recycling, and also avoid using

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toxic materials such as mercury in production (Mercury-Containing and Rechargeable Battery Management Act in 1996). Therefore, such mentioned concerns and regulations engage battery producers to contribute to the battery recovery and recycling.

Some methodologies related to RL and CLSC were reviewed to cover decision making in all possible categories such as certain, uncertain, and risky situations in Chapter 2. Applications of MILP, stochastic (scenario-based analysis), and fuzzy programming were chosen as the main fields of this study.

Initially, a deterministic model for a multi-echelon, multi-components, multi-product, multiperiod battery CLSC in a realistic network was proposed in Chapter 3. The solution for the proposed deterministic model indicated the objective optimal values, and decision variables with regard to multiple periods. Furthermore, the optimal binary variables included 2 suppliers, 1 location for plant, 5 retailers, and 2 locations for battery recovery centers. Scenario-based analysis was utilized to evaluate the response of proposed model under the risks of unexpected changes in demand and return. Since, the possibility of occurrence of each scenario can be identified based on experts' judgment, all possible combinations of 10 percent changes in market's demand and returned product were investigated. Then, comparing the objective values of the provided scenarios proved that the expected profit of the battery CLSC is very sensitive to the unexpected changes in demand and returned. To figure out the importance of efficiency in CLSC, sensitivity analysis was conducted on disposal fraction. According to the findings, disposal fraction had major reverse impact on profit of battery CLSC. In other words, efficiency in recycling of used battery can enhance CLSC profit and reduce the environmental issues significantly.

Some related studies were considered to determine the green performance indicators in a battery CLSC in Chapter 4. The fuzzy ANP method was utilized based on Chang's method. The overall priorities of plants and battery recovery centers were measured with regard to the proposed green practice frameworks. According to linguistic scale of relative importance, all criteria were compared. Thereafter, pairwise comparisons were applied to all sub-criteria, and then all plants and battery recovery centers were prioritized based on green performance.

The preliminary concepts of using arithmetic operations for triangular fuzzy numbers were discussed in Chapter 5. The application of FFP approach was explained for the proposed battery CLSC. The solution included the optimal range of objective function and decision variables. To

develop the possible alternatives, scenario-based analysis was integrated with FFP method to consider different cases for lower range, middle range, and upper range of demand and return. The results indicated changes in demand have more impacts on total expected profit of battery CLSC in comparison with return. To consider the green performance of plants and battery recovery centres under uncertainty, the fuzzy multi-objective approach was employed. Hence, each fuzzy problem was solved separately, and then distance technique and &-constraint method were utilized to find the trade-off solution of multi-objective FFP model.

6.3. Recommendations for future research

There are some potential complementary research areas for this study in aspects of environmental issues, different transportation strategies, financial and economic indicators, robust optimization, and metaheuristic optimization as follows:

Developing mathematical models to consider environmental issues

In Chapter 4, a fuzzy ANP method was utilized to convert the qualitative indicators of green performance to the quantitative parameters for plants and battery recovery centres. Furthermore, it will be commonsensical, if the proposed battery CLSC is developed to the multi-objective optimization model with more environmental factors. New environmental objectives can be defined for the CLSC such as minimization of carbon emission, fuel and energy consumption, solid and septic waste in addition to the maximization of total profit.

Developing mathematical models to consider different transportation strategies

One of the main strategies to reduce the environmental impacts of CLSC is associated with transportation sectors. Hence, role of transportation strategies can be considered in the optimization model. For further clarification, the proposed CLSC model can be developed by the following scenarios; the finished products can be delivered to the retailers in a single shipment after manufacturing of all markets' demand, or the finished products can be delivered to the retailers delivered to the retailers separately (in multiple shipments) upon after manufacturing of each markets' demand.

Developing mathematical models to consider financial and economic indicators

The total profit of CLSCs are dependent to the variety of financial and economic factors such as inflation rate, interest rate, exchange rate, cost of energy and labor force along with depreciation cost of all assets and machines belonging to the CLSCs. All mentioned factors can contribute to the optimization of CLSC network through the maximization of net present value (NPV) of discounted cash flows related to each period.

Developing solution approaches to consider robust optimization

There are some potential complementary research areas to address uncertainty. In this thesis, fuzzy and scenario-based analysis were utilized to solve the proposed model. To deal with imprecise information, robust optimization can be applied as well. Contrary to the scenario-based analysis, probability of each scenario is unknown in robust optimization. For different types of uncertainties, robust optimization can be utilized due to its computational flexibility.

Developing solution approaches to consider metaheuristic optimization

In real optimization problems, it is highly probable to confront multi-objective, non-linear mathematical models with regard to complicated constraints. Hence, different objectives may have conflict with each other leading to difficult optimization problems. In such cases, metaheuristic algorithms can be applied to reach good solutions, but there is not any guarantee to reach optimal solutions.

APPENDIX A. FUZZY ANP ANALYSES TO RANK THE PLANTS BASED ON THE GREEN PERFORMANCE Table A.1

Priority of each plant with respect to Sc_1

Sc_1		Plant 1			Plant 2	r.		Plant 3			Plant 4			Plant 5			W_c		
Plant 1	1.00	1.00	1.00	1.00	1.50	2.00	1.00	1.50	2.00	1.50	2.00	2.50	0.50	1.00	1.50	1.00	1.50	2.00	0.211
Plant 2	0.50	0.67	1.00	1.00	1.00	1.00	1.00	1.50	2.00	1.00	1.50	2.00	1.00	1.50	2.00	0.50	1.00	1.50	0.183
Plant 3	0.50	0.67	1.00	0.50	0.67	1.00	1.00	1.00	1.00	0.50	1.00	1.50	1.00	1.50	2.00	2.00	2.50	3.00	0.186
Plant 4	0.40	0.50	0.67	0.50	0.67	1.00	0.67	1.00	2.00	1.00	1.00	1.00	0.50	1.00	1.50	1.00	1.50	2.00	0.149
Plant 5	0.67	1.00	2.00	0.50	0.67	1.00	0.50	0.67	1.00	0.67	1.00	2.00	1.00	1.00	1.00	1.00	1.50	2.00	0.158
Plant 6	0.50	0.67	1.00	0.67	1.00	2.00	0.33	0.40	0.50	0.50	0.67	1.00	0.50	0.67	1.00	1.00	1.00	1.00	0.111

Table A.2

Priority of each plant with respect to Sc₂

Thomy		plant	with it.	speet it	$J \operatorname{SC}_2$														
Sc_2		Plant 1			Plant 2			Plant 3			Plant 4			Plant 5				W_c	
Plant 1	1.00	1.00	1.00	2.00	2.50	3.00	1.00	1.50	2.00	1.50	2.00	2.50	0.50	1.00	1.50	1.00	1.50	2.00	0.232
Plant 2	0.33	0.40	0.50	1.00	1.00	1.00	1.50	2.00	2.50	1.00	1.50	2.00	1.00	1.50	2.00	2.00	2.50	3.00	0.219
Plant 3	0.50	0.67	1.00	0.40	0.50	0.67	1.00	1.00	1.00	2.00	2.50	3.00	1.00	1.50	2.00	0.50	1.00	1.50	0.177
Plant 4	0.40	0.50	0.67	0.50	0.67	1.00	0.33	0.40	0.50	1.00	1.00	1.00	0.50	1.00	1.50	1.00	1.50	2.00	0.111
Plant 5	0.67	1.00	2.00	0.50	0.67	1.00	0.50	0.67	1.00	0.67	1.00	2.00	1.00	1.00	1.00	0.50	1.00	1.50	0.142
Plant 6	0.50	0.67	1.00	0.33	0.40	0.50	0.67	1.00	2.00	0.50	0.67	1.00	0.67	1.00	2.00	1.00	1.00	1.00	0.121

Table A.3

Table A.3		
Priority of each	plant with res	pect to Sc_3

Sc_3		Plant 1			Plant 2			Plant 3			Plant 4			Plant 5			W_c		
Plant 1	1.00	1.00	1.00	1.00	1.50	2.00	2.00	2.50	3.00	1.50	2.00	2.50	0.50	1.00	1.50	2.00	2.50	3.00	0.262
Plant 2	0.50	0.67	1.00	1.00	1.00	1.00	1.00	1.50	2.00	2.00	2.50	3.00	1.00	1.50	2.00	0.50	1.00	1.50	0.206
Plant 3	0.33	0.40	0.50	0.50	0.67	1.00	1.00	1.00	1.00	0.50	1.00	1.50	1.50	2.00	2.50	1.00	1.50	2.00	0.157
Plant 4	0.40	0.50	0.67	0.33	0.40	0.50	0.67	1.00	2.00	1.00	1.00	1.00	2.00	2.50	3.00	1.50	2.00	2.50	0.185
Plant 5	0.67	1.00	2.00	0.50	0.67	1.00	0.40	0.50	0.67	0.33	0.40	0.50	1.00	1.00	1.00	1.00	1.50	2.00	0.112
Plant 6	0.33	0.40	0.50	0.67	1.00	2.00	0.50	0.67	1.00	0.40	0.50	0.67	0.50	0.67	1.00	1.00	1.00	1.00	0.078

Table A.4 Priority of each plant with respect to Sc_4

Sc_4		Plant 1			Plant 2			Plant 3	1		Plant 4			Plant 5			W_c		
Plant 1	1.00	1.00	1.00	2.00	2.50	3.00	1.00	1.50	2.00	1.50	2.00	2.50	0.50	1.00	1.50	2.00	2.50	3.00	0.262
Plant 2	0.33	0.40	0.50	1.00	1.00	1.00	1.00	1.50	2.00	1.00	1.50	2.00	1.00	1.50	2.00	0.50	1.00	1.50	0.169
Plant 3	0.50	0.67	1.00	0.50	0.67	1.00	1.00	1.00	1.00	0.50	1.00	1.50	2.00	2.50	3.00	0.50	1.00	1.50	0.168
Plant 4	0.40	0.50	0.67	0.50	0.67	1.00	0.67	1.00	2.00	1.00	1.00	1.00	0.50	1.00	1.50	1.50	2.00	2.50	0.153
Plant 5	0.67	1.00	2.00	0.50	0.67	1.00	0.33	0.40	0.50	0.67	1.00	2.00	1.00	1.00	1.00	1.00	1.50	2.00	0.142
Plant 6	0.33	0.40	0.50	0.67	1.00	2.00	0.67	1.00	2.00	0.40	0.50	0.67	0.50	0.67	1.00	1.00	1.00	1.00	0.106

Table A.5

Priority of each plant with respect to Sc₅

Thomy	or each	piane		speeru	0.005														
Sc_5		Plant 1			Plant 2			Plant 3			Plant 4			Plant 5				W_c	
Plant 1	1.00	1.00	1.00	2.00	2.50	3.00	1.00	1.50	2.00	2.00	2.50	3.00	1.00	1.50	2.00	2.00	2.50	3.00	0.312
Plant 2	0.33	0.40	0.50	1.00	1.00	1.00	1.00	1.50	2.00	1.00	1.50	2.00	0.50	1.00	1.50	0.50	1.00	1.50	0.156
Plant 3	0.50	0.67	1.00	0.50	0.67	1.00	1.00	1.00	1.00	0.50	1.00	1.50	1.00	1.50	2.00	1.00	1.50	2.00	0.155
Plant 4	0.33	0.40	0.50	0.50	0.67	1.00	0.67	1.00	2.00	1.00	1.00	1.00	1.00	1.50	2.00	2.00	2.50	3.00	0.185
Plant 5	0.50	0.67	1.00	0.67	1.00	2.00	0.50	0.67	1.00	0.50	0.67	1.00	1.00	1.00	1.00	1.00	1.50	2.00	0.133
Plant 6	0.33	0.40	0.50	0.67	1.00	2.00	0.50	0.67	1.00	0.33	0.40	0.50	0.50	0.67	1.00	1.00	1.00	1.00	0.058

Tal	ble 4	A.6
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Priority of each plant with respect to Sc_{d}	ct to Sc_6	with respec	plant	each	of	Priority	
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Sc_6		Plant 1			Plant 2			Plant 3			Plant 4			Plant 5			Plant 6	j	W_c
Plant 1	1.00	1.00	1.00	1.00	1.50	2.00	0.50	1.00	1.50	1.50	2.00	2.50	0.50	1.00	1.50	1.00	1.50	2.00	0.198
Plant 2	0.50	0.67	1.00	1.00	1.00	1.00	2.00	2.50	3.00	1.00	1.50	2.00	1.50	2.00	2.50	0.50	1.00	1.50	0.212
Plant 3	0.67	1.00	2.00	0.33	0.40	0.50	1.00	1.00	1.00	0.50	1.00	1.50	1.00	1.50	2.00	0.50	1.00	1.50	0.151
Plant 4	0.40	0.50	0.67	0.50	0.67	1.00	0.67	1.00	2.00	1.00	1.00	1.00	1.00	1.50	2.00	2.00	2.50	3.00	0.180
Plant 5	0.67	1.00	2.00	0.40	0.50	0.67	0.50	0.67	1.00	0.50	0.67	1.00	1.00	1.00	1.00	1.00	1.50	2.00	0.134
Plant 6	0.50	0.67	1.00	0.67	1.00	2.00	0.67	1.00	2.00	0.33	0.40	0.50	0.50	0.67	1.00	1.00	1.00	1.00	0.124

Table A.7Priority of each plant with respect to Sc7

Sc_7	Plant 1			Plant 2	,		Plant 3	5		Plant 4			Plant 5	i		Plant 6)	W_c	
Plant 1	1.00	1.00	1.00	1.00	1.50	2.00	2.00	2.50	3.00	1.50	2.00	2.50	0.50	1.00	1.50	2.00	2.50	3.00	0.270
Plant 2	0.50	0.67	1.00	1.00	1.00	1.00	1.00	1.50	2.00	1.00	1.50	2.00	1.00	1.50	2.00	0.50	1.00	1.50	0.184
Plant 3	0.33	0.40	0.50	0.50	0.67	1.00	1.00	1.00	1.00	0.50	1.00	1.50	1.00	1.50	2.00	1.00	1.50	2.00	0.145
Plant 4	0.40	0.50	0.67	0.50	0.67	1.00	0.67	1.00	2.00	1.00	1.00	1.00	0.50	1.00	1.50	0.50	1.00	1.50	0.126
Plant 5	0.67	1.00	2.00	0.50	0.67	1.00	0.50	0.67	1.00	0.67	1.00	2.00	1.00	1.00	1.00	1.00	1.50	2.00	0.157
Plant 6	0.33	0.40	0.50	0.67	1.00	2.00	0.50	0.67	1.00	0.67	1.00	2.00	0.50	0.67	1.00	1.00	1.00	1.00	0.118

Table A.8

Priority of each plant with respect to Sc_8

Filolity of each plant with respect to 5c8																			
Sc_8		Plant 1			Plant 2			Plant 3			Plant 4			Plant 5	i		Plant 6	Ď	W_c
Plant 1	1.00	1.00	1.00	1.00	1.50	2.00	1.00	1.50	2.00	1.50	2.00	2.50	0.50	1.00	1.50	1.00	1.50	2.00	0.214
Plant 2	0.50	0.67	1.00	1.00	1.00	1.00	2.00	2.50	3.00	1.00	1.50	2.00	1.50	2.00	2.50	1.00	1.50	2.00	0.229
Plant 3	0.50	0.67	1.00	0.33	0.40	0.50	1.00	1.00	1.00	0.50	1.00	1.50	1.00	1.50	2.00	0.50	1.00	1.50	0.135
Plant 4	0.40	0.50	0.67	0.50	0.67	1.00	0.67	1.00	2.00	1.00	1.00	1.00	0.50	1.00	1.50	1.00	1.50	2.00	0.145
Plant 5	0.67	1.00	2.00	0.40	0.50	0.67	0.50	0.67	1.00	0.67	1.00	2.00	1.00	1.00	1.00	2.00	2.50	3.00	0.175
Plant 6	0.50	0.67	1.00	0.50	0.67	1.00	0.67	1.00	2.00	0.50	0.67	1.00	0.33	0.40	0.50	1.00	1.00	1.00	0.102

Table A.9 Priority of each plant with respect to *Sc*₉

Sc_9		Plant 1			Plant 2			Plant 3			Plant 4			Plant 5	i		Plant 6	j	W_c
Plant 1	1.00	1.00	1.00	1.00	1.50	2.00	1.50	2.00	2.50	2.00	2.50	3.00	0.50	1.00	1.50	1.00	1.50	2.00	0.235
Plant 2	0.50	0.67	1.00	1.00	1.00	1.00	1.00	1.50	2.00	1.00	1.50	2.00	1.00	1.50	2.00	0.50	1.00	1.50	0.181
Plant 3	0.40	0.50	0.67	0.50	0.67	1.00	1.00	1.00	1.00	0.50	1.00	1.50	1.00	1.50	2.00	2.00	2.50	3.00	0.179
Plant 4	0.33	0.40	0.50	0.50	0.67	1.00	0.67	1.00	2.00	1.00	1.00	1.00	0.50	1.00	1.50	0.50	1.00	1.50	0.127
Plant 5	0.67	1.00	2.00	0.50	0.67	1.00	0.50	0.67	1.00	0.67	1.00	2.00	1.00	1.00	1.00	1.00	1.50	2.00	0.156
Plant 6	0.50	0.67	1.00	0.67	1.00	2.00	0.33	0.40	0.50	0.67	1.00	2.00	0.50	0.67	1.00	1.00	1.00	1.00	0.122

Table A.10

i nonty of each plant with respect to be 10	iority of each plan	t with respect to Sc_{10}
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<i>Sc</i> ₁₀		Plant 1			Plant 2	, ,		Plant 3			Plant 4			Plant 5			Plant 6	ō	W_c
Plant 1	1.00	1.00	1.00	1.00	1.50	2.00	1.00	1.50	2.00	1.50	2.00	2.50	1.00	1.50	2.00	1.00	1.50	2.00	0.225
Plant 2	0.50	0.67	1.00	1.00	1.00	1.00	1.00	1.50	2.00	1.00	1.50	2.00	1.00	1.50	2.00	0.50	1.00	1.50	0.184
Plant 3	0.50	0.67	1.00	0.50	0.67	1.00	1.00	1.00	1.00	0.50	1.00	1.50	1.00	1.50	2.00	2.00	2.50	3.00	0.187
Plant 4	0.40	0.50	0.67	0.50	0.67	1.00	0.67	1.00	2.00	1.00	1.00	1.00	0.50	1.00	1.50	1.00	1.50	2.00	0.148
Plant 5	0.50	0.67	1.00	0.50	0.67	1.00	0.50	0.67	1.00	0.67	1.00	2.00	1.00	1.00	1.00	1.50	2.00	2.50	0.157
Plant 6	0.50	0.67	1.00	0.67	1.00	2.00	0.33	0.40	0.50	0.50	0.67	1.00	0.40	0.50	0.67	1.00	1.00	1.00	0.099

APPENDIX B. FUZZY ANP ANALYSES TO RANK THE BATTERY RECOVERY CENTERS BASED ON THE GREEN PERFORMANCE

Table B.1

Pairwise comparisons among criteria

Fally															
We_1		C_1			C_2			C_3		W_c					
C_1	1	1	1	0.5	1	1.5	1	1.5	2	0.39					
C_2	0.67	1	2	1	1	1	1.5	2	2.5	0.45					
C_3	0.5	0.67	1	0.4	0.5	0.67	1	1.	1	0.16					

Table B.2

The ini	ner depende	ence matrix	k and rela	tive impo	rtance weig	ght with	respect to C_1
C_1		C_2			C_3		W_c
C_2	1	1	1	1	1.5	2	0.68
C_3	0.5	0.67	1	1	1	1	0.32

Table B.3

The in	ner depender	nce matri	ix and rela	tive impor	tance wei	ght with r	espect to C_2
C_2		C_1			C_3		W_c
C_1	1	1	1	0.5	1	1.5	0.50
C_{3}	0.67	1	2	1	1	1	0.50

Table B.4

The inner dependence matrix and relative importance weight with respect to C_3

C_3		C_1			C_2		W_c
C_1	1	1	1	1	1.5	2	0.68
C_2	0.5	0.67	1	1	1	1	0.32

The relate	d priorities of th	e green perfo	rmance criteria	a for battery 1	recovery centers
We_2	C_{l}	C_2	C_3	We_1	$We_{criteria} = We_2^* We_1$
C_1	1	0.5	0.68	0.39	0.36
C_2	0.68	1	0.32	0.45	0.38
C_3	0.32	0.5	1	0.16	0.25

Table B.5

Table B.6

Pairwise comparisons among sub-criteria of C_1

C_1		Sc_1			Sc_2		W_c
Sc_1	1	1	1	0.5	0.67	1	0.32
Sc_2	1	1.5	2	1	1	1	0.68

Table B.7

Pairwise comparisons among sub-criteria of C_2

C_2		Sc_3			Sc_4			Sc_5		W_c
Sc_3	1	1	1	0.5	1	1.5	1.5	2	2.5	0.41
Sc_4	0.67	1	2	1	1	1	0.5	1	1.5	0.33
Sc_5	0.4	0.5	0.67	0.67	1	2	1	1	1	0.26

Table B.8

comparisons			

C_3		Sc_6			Sc_7		W_c
Sc_6	1	1	1	1	1.5	2	0.68
Sc_7	0.5	0.67	1	1	1	1	0.32

We_{sub-criteria} We_{criteria} obtained We_{sub-criteria}, Fuzzy ANP Sub-criteria obtained in in Step 4 (overall) Step 5 Sc1: Utilizing eco-intelligent technology for sorting 0.32 0.11 *C*₁: Eco-intelligent returned batteries 0.36 technology Sc2: Utilizing eco-intelligent technology for recycling 0.68 0.25 batteries 0.16 0.41 Sc3: Responsible Recycling© (R2) Certification *C*₂: Environmental practice 0.12 0.38 0.33 Sc4: Solid and septic waste management 0.26 0.10 Sc5: Environmental Regulatory Compliance 0.68 0.17 Sc6: Collaborating with customer *C*₃: battery recovery service 0.25 0.32 0.08 Sc7: Maintenance and inspection for reducing scrap rate

 Table B.9

 Overall priority of the sub-criteria of green performance for potential battery recovery centers

Sc_1	R	ec. cente	r 1	Re	ec. center	2	Rec	. center	3	Re	c. cente	r 4	R	ec. cente	er 5	Re	c. center	6	Re	c. cente	r 7	R	ec. cente	er 8	Re	c. cente	r 9	Re	c. cente	r 10	\mathbf{W}_{c}
Rec. center 1	1	1	1	1	1.5	2	1	1.5	2	1.5	2	2.5	0.5	1	1.5	1	1.5	2	1.5	2	2.5	0.5	1	1.5	2	2.5	3	2	2.5	3	0.14
Rec. center 2	0.5	0.67	1	1	1	1	1	1.5	2	1	1.5	2	1	1.5	2	0.5	1	1.5	2	2.5	3	1	1.5	2	0.5	1	1.5	0.5	1	1.5	0.12
Rec. center 3	0.5	0.67	1	0.5	0.67	1	1	1	1	0.5	1	1.5	1	1.5	2	0.5	1	1.5	0.5	1	1.5	0.5	1	1.5	1	1.5	2	1	1.5	2	0.10
Rec. center 4	0.4	0.5	0.67	0.5	0.67	1	0.67	1	2	1	1	1	0.5	1	1.5	1	1.5	2	2	2.5	3	0.5	1	1.5	0.5	1	1.5	0.5	1.	1.5	0.10
Rec. center 5	0.67	1	2	0.5	0.67	1	0.5	0.67	1	0.67	1	2	1	1	1	1	1.5	2	2	2.5	3	1.5	2	2.5	1	1.5	2	1.5	2	2.5	0.12
Rec. center 6	0.5	0.67	1	0.67	1	2	0.67	1	2	0.5	0.67	1	0.5	0.67	1	1	1	1	1	1.5	2	0.5	1	1.5	0.5	1	1.5	1	1.5	2	0.09
Rec. center 7	0.4	0.5	0.67	0.33	0.4	0.5	0.67	1	2	0.33	0.4	0.5	0.33	0.4	0.5	0.5	0.67	1	1	1	1	0.5	1	1.5	0.5	1	1.5	0.5	1	1.5	0.06
Rec. center 8	0.67	1	2	0.5	0.67	1	0.67	1	2	0.67	1	2	0.4	0.5	0.67	0.67	1	2	0.67	1	2	1	1	1	1.5	2	2.5	1	1.5	2	0.10
Rec. center 9	0.33	0.4	0.5	0.67	1	2	0.5	0.67	1	0.67	1	2	0.5	0.67	1	0.67	1	2	0.67	1	2	0.4	0.5	0.67	1	1	1	2	2.5	3	0.09
Rec. center 10	0.33	0.4	0.5	0.67	1	2	0.5	0.67	1	0.67	1	2	0.4	0.5	0.67	0.5	0.67	1	0.67	1	2	0.5	0.67	1	0.33	0.4	0.5	1	1	1	0.07

Table B.10Priority of each battery recovery center with respect to Sc1

Table B.11 Priority of each battery recovery center with respect to Sc_2

Sc ₂	R	ec. cente	r 1	Re	c. center	r 2	Rec	. center	3	Re	c. cente	r 4	R	ec. cente	r 5	Re	c. cente	r 6	Re	c. cente	r 7	Ree	c. cente	er 8	Re	ec. cente	r 9	Red	c. cente	er 10	\mathbf{W}_{c}
Rec. center 1	1	1	1	1	1.5	2	1	1.5	2	1.5	2	2.5	2	2.5	3	1	1.5	2	1.5	2	2.5	2	2.5	3	0.5	1	1.5	2	2.5	3	0.16
Rec. center 2	0.5	0.67	1	1	1	1	1	1.5	2	1	1.5	2	1	1.5	2	0.5	1	1.5	2	2.5	3	0.5	1	1.5	0.5	1	1.5	0.5	1	1.5	0.11
Rec. center 3	0.5	0.67	1	0.5	0.67	1	1	1	1	0.5	1	1.5	1	1.5	2	0.5	1	1.5	0.5	1	1.5	0.5	1	1.5	1	1.5	2	1	1.5	2	0.10
Rec. center 4	0.4	0.5	0.67	0.5	0.67	1	0.67	1	2	1	1	1	0.5	1	1.5	1	1.5	2	1	1.5	2	2	2.5	3	0.5	1	1.5	0.5	1	1.5	0.11
Rec. center 5	0.33	0.4	0.5	0.5	0.67	1	0.5	0.67	1	0.67	1	2	1	1	1	1	1.5	2	2	2.5	3	0.5	1	1.5	0.5	1	1.5	1.5	2	2.5	0.11
Rec. center 6	0.5	0.67	1	0.67	1	2	0.67	1	2	0.5	0.67	1	0.5	0.67	1	1	1	1	0.5	1	1.5	0.5	1	1.5	1	1.5	2	2	2.5	3	0.10
Rec. center 7	0.4	0.5	0.67	0.33	0.4	0.5	0.67	1	2	0.5	0.67	1	0.33	0.4	0.5	0.67	1	2	1	1	1	0.5	1	1.5	0.5	1	1.5	0.5	1	1.5	0.07
Rec. center 8	0.33	0.4	0.5	0.67	1	2	0.67	1	2	0.33	0.4	0.5	0.67	1	2	0.67	1	2	0.67	1	2	1	1	1	0.5	1	1.5	0.5	1	1.5	0.09
Rec. center 9	0.67	1	2	0.67	1	2	0.5	0.67	1	0.67	1	2	0.67	1	2	0.5	0.67	1	0.67	1	2	0.67	1	2	1	1	1	1	1.5	2	0.10
Rec. center 10	0.33	0.4	0.5	0.67	1	2	0.5	0.67	1	0.67	1	2	0.4	0.5	0.67	0.33	0.4	0.5	0.67	1	2	0.67	1	2	0.5	0.67	1	1	1	1	0.07

Table B.12	
Priority of each battery recovery center w	with respect to Sc3

Sc3	Re	ec. cente	r 1	R	ec. cente	r 2		Rec. cen	ter 3		Rec. c	enter 4		Rec. o	center 5		Rec.	center 6		Rec.	center 7	7	Rec.	center 8	3	Rec.	center 9		Rec. c	enter 1	0 W _c
Rec. center 1	1	1	1	2	2.5	3	1	1.5	2	1.5	2	2.5	2	2.5	3	1	1.5	2	2	2.5	3	1	1.5	2	0.5	1	1.5	2	2.5	3	0.16
Rec. center 2	0.33	0.4	0.5	1	1	1	1	1.5	2	1	1.5	2	1	1.5	2	0.5	1	1.5	2	2.5	3	0.5	1	1.5	1.5	2	2.5	1.5	2	2.5	0.13
Rec. center 3	0.5	0.67	1	0.5	0.67	1	1	1	1	0.5	1	1.5	1	1.5	2	0.5	1	1.5	0.5	1	1.5	1.5	2	2.5	0.5	1	1.5	1	1.5	2	0.10
Rec. center 4	0.4	0.5	0.67	0.5	0.67	1	0.67	1	2	1	1	1	0.5	1	1.5	1	1.5	2	2	2.5	3	0.5	1	1.5	1	1.5	2	0.5	1	1.5	0.10
Rec. center 5	0.33	0.4	0.5	0.5	0.67	1	0.5	0.67	1	0.67	1	2	1	1	1	1	1.5	2	2	2.5	3	1	1.5	2	1.5	2	2.5	1.5	2	2.5	0.12
Rec. center 6	0.5	0.67	1	0.67	1	2	0.67	1	2	0.5	0.67	1	0.5	0.67	1	1	1	1	1	1.5	2	1.5	2	2.5	0.5	1	1.5	0.5	1	1.5	0.10
Rec. center 7	0.33	0.4	0.5	0.33	0.4	0.5	0.67	1	2	0.33	0.4	0.5	0.33	0.4	0.5	0.5	0.67	1	1	1	1	0.5	1	1.5	0.5	1	1.5	2	2.5	3	0.07
Rec. center 8	0.5	0.67	1	0.67	1.0	2	0.4	0.5	0.67	0.67	1	2	0.5	0.67	1	0.4	0.5	0.67	0.67	1	2	1	1	1	2	2.5	3	0.5	1	1.5	0.09
Rec. center 9	0.67	1.0	2	0.4	0.5	0.67	0.67	1	2.	0.5	0.67	1	0.4	0.5	0.67	0.67	1	2	0.67	1	2	0.33	0.4	0.5	1	1	1	1.5	2	2.5	0.08
Rec. center 10	0.33	0.4	0.5	0.4	0.5	0.67	0.5	0.67	1	0.67	1	2	0.4	0.5	0.67	0.67	1	2	0.33	0.4	0.5	0.67	1	2	0.4	0.5	0.67	1	1	1	0.05

Table B.13
Priority of each battery recovery center with respect to Sc ₄

Sc ₄	Re	ec. cente	r 1	Re	c. center	2	Re	ec. cente	er 3	Re	ec. cente	er 4	Re	ec. cente	er 5	Re	c. cent	er 6	Re	ec. cent	er 7	Re	c. cente	r 8	Re	c. cente	er 9	Rec	c. cente	r 10	Wc
Rec. center 1	1	1	1	1	1.5	2	2	2.5	3	1.5	2	2.5	0.5	1	1.5	1.5	2	2.5	0.5	1	1.5	2	2.5	3	1	1.5	2	2	2.5	3	0.15
Rec. center 2	0.5	0.67	1	1	1	1	1	1.5	2	1	1.5	2	1	1.5	2	0.5	1	1.5	2	2.5	3	0.5	1	1.5	0.5	1	1.5	0.5	1	1.5	0.11
Rec. center 3	0.33	0.4	0.5	0.5	0.67	1	1	1	1	0.5	1	1.5	1	1.5	2	0.5	1	1.5	1.5	2	2.5	0.5	1	1.5	1	1.5	2	2	2.5	3	0.11
Rec. center 4	0.4	0.5	0.67	0.5	0.67	1	0.67	1	2	1	1	1	0.5	1	1.5	1	1.5	2	0.5	1	1.5	1.5	2	2.5	0.5	1	1.5	0.5	1	1.5	0.10
Rec. center 5	0.67	1	2	0.5	0.67	1	0.5	0.67	1	0.67	1	2	1	1	1	1	1.5	2	2	2.5	3	0.5	1	1.5	2	2.5	3	1.5	2	2.5	0.12
Rec. center 6	0.4	0.5	0.67	0.67	1	2	0.67	1	2	0.5	0.67	1	0.5	0.67	1	1	1	1	1.5	2	2.5	1.5	2	2.5	0.5	1	1.5	1.5	2	2.5	0.11
Rec. center 7	0.67	1	2	0.33	0.4	0.5	0.4	0.5	0.67	0.67	1	2	0.33	0.4	0.5	0.4	0.5	0.67	1	1	1	0.5	1	1.5	1.5	2	2.5	0.5	1	1.5	0.08
Rec. center 8	0.33	0.4	0.5	0.67	1	2	0.67	1	2	0.4	0.5	0.67	0.67	1	2	0.4	0.5	0.67	0.67	1	2	1	1	1	0.5	1	1.5	1	1.5	2	0.08
Rec. center 9	0.5	0.67	1	0.67	1	2	0.5	0.67	1	0.67	1	2	0.33	0.4	0.5	0.67	1	2	0.4	0.5	0.67	0.67	1	2	1	1	1	2	2.5	3	0.09
Rec. center 10	0.33	0.4	0.5	0.67	1	2	0.33	0.4	0.5	0.67	1	2	0.4	0.5	0.67	0.4	0.5	0.67	0.67	1	2	0.50	0.67	1	0.33	0.4	0.5	1	1	1	0.05

Sc5	Re	ec. cente	r 1	Re	ec. cente	er 2	Re	c. center	3	Re	c. cente	r 4	Re	c. cente	r 5	R	ec. cente	er 6	Re	c. cente	er 7	Re	c. cente	er 8	R	.ec. cen	ter 9		Rec. cent	er 10	\mathbf{W}_{c}
Rec. center 1	1	1	1	1	1.5	2	1	1.5	2	1.5	2	2.5	0.5	1	1.5	1	1.5	2	1.5	2	2.5	0.5	1	1.5	1	1.5	2	2	2.5	3	0.13
Rec. center 2	0.5	0.67	1	1	1	1	1	1.5	2	1	1.5	2	1	1.5	2	0.5	1	1.5	2	2.5	3	1.5	2	2.5	0.5	1	1.5	0.5	1	1.5	0.12
Rec. center 3	0.5	0.67	1	0.5	0.67	1	1	1	1	2	2.5	3	1	1.5	2	2	2.5	3	0.5	1	1.5	0.5	1	1.5	0.5	1	1.5	1	1.5	2	0.11
Rec. center 4	0.4	0.5	0.67	0.5	0.67	1	0.33	0.4	0.5	1	1	1	0.5	1	1.5	1	1.5	2	0.5	1	1.5	1	1.5	2	2	2.5	3	0.5	1	1.5	0.10
Rec. center 5	0.67	1	2	0.5	0.67	1	0.5	0.67	1	0.67	1	2	1	1	1	1	1.5	2	2	2.5	3	0.5	1	1.5	0.5	1	1.5	2	2.5	3	0.11
Rec. center 6	0.5	0.67	1	0.67	1	2	0.33	0.4	0.5	0.5	0.67	1	0.5	0.67	1	1	1	1	2	2.5	3	1.5	2	2.5	1	1.5	2	2	2.5	3	0.11
Rec. center 7	0.4	0.5	0.67	0.33	0.4	0.5	0.67	1	2	0.67	1	2	0.33	0.4	0.5	0.33	0.4	0.5	1	1	1	0.5	1	1.5	0.5	1	1.5	0.5	1	1.5	0.07
Rec. center 8	0.67	1	2	0.4	0.5	0.67	0.67	1	2	0.5	0.67	1	0.67	1	2	0.4	0.5	0.67	0.67	1	2	1	1	1	1.5	2	2.5	2	2.5	3	0.10
Rec. center 9	0.5	0.67	1	0.67	1	2	0.67	1	2	0.33	0.4	0.5	0.67	1	2	0.5	0.67	1	0.67	1	2	0.4	0.5	0.67	1	1	1	2	2.5	3	0.09
Rec. center 10	0.33	0.4	0.5	0.67	1	2	0.5	0.67	1	0.67	1	2	0.33	0.4	0.5	0.33	0.4	0.5	0.67	1	2	0.33	0.4	0.5	0.33	0.4	0.5	1	1	1	0.06

Table B.14 Priority of each battery recovery center with respect to Sc_5

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Priority of each battery recovery center with respect to Sc₆

Sc_6	R	ec. cente	er 1	Re	c. center	2	Re	c. center	• 3	Re	ec. cente	er 4	Re	c. center	: 5	Re	c. center	6	R	ec. cente	r 7	Re	c. cente	r 8	Ree	c. cente	r 9	Red	c. cente	r 10	Wc
Rec. center 1	1	1	1	1	1.5	2	1	1.5	2	1.5	2	2.5	0.5	1	1.5	1	1.5	2	2	2.5	3	0.5	1	1.5	2	2.5	3	1.5	2	2.5	0.14
Rec. center 2	0.5	0.67	1	1	1	1	1	1.5	2	1	1.5	2	1	1.5	2	0.5	1	1.5	2	2.5	3	1	1.5	2	1	1.5	2	2	2.5	3	0.13
Rec. center 3	0.5	0.67	1	0.5	0.67	1	1	1	1	0.5	1	1.5	2.	2.5	3	0.5	1	1.5	0.5	1	1.5	0.5	1	1.5	0.5	1	1.5	1	1	2	0.10
Rec. center 4	0.4	0.5	0.67	0.5	0.67	1	0.67	1	2	1	1	1	2	2.5	3	1	1.5	2	0.5	1	1.5	2	2.5	3	2	2.5	3	1.5	2	2.5	0.13
Rec. center 5	0.67	1	2	0.5	0.67	1	0.33	0.4	0.5	0.33	0.4	0.5	1	1	1	2	2.5	3	1	1.5	2	2	2.5	3.	0.5	1	1.5	2	2.5	3	0.12
Rec. center 6	0.5	0.67	1	0.67	1	2	0.67	1	2	0.5	0.67	1	0.33	0.4	0.5	1	1	1.	0.5	1	1.5	0.5	1	1.5	1	1.5	2	0.5	1	1.5	0.08
Rec. center 7	0.33	0.4	0.5	0.33	0.4	0.5	0.67	1	2	0.67	1	2	0.5	0.67	1	0.67	1	2	1	1	1	1.5	2	2.5	0.5	1	1.5	1	1.5	2	0.09
Rec. center 8	0.67	1	2	0.5	0.67	1	0.67	1	2	0.33	0.4	0.5	0.33	0.4	0.5	0.67	1	2	0.4	0.5	0.67	1	1	1	0.5	1	1.5	0.5	1	1.5	0.07
Rec. center 9	0.33	0.4	0.5	0.5	0.67	1	0.67	1	2	0.33	0.4	0.5	0.67	1	2	0.5	0.67	1	0.67	1	2	0.67	1	2	1	1	1	2	2.5	3	0.09
Rec. center 10	0.4	0.5	0.67	0.33	0.4	0.5	0.5	0.67	1	0.4	0.5	0.67	0.33	0.4	0.5	0.67	1	2	0.5	0.67	1	0.67	1	2	0.33	0.4	0.5	1	1	1	0.05

Sc7	Re	ec. cente	r 1	R	ec. cente	er 2	Re	c. center	3	Re	c. cente	er 4	Re	ec. cente	er 5	Re	ec. cente	er 6	R	ec. cente	er 7	Re	c. center	8	Re	c. cente	r 9	Red	c. cente	r 10	\mathbf{W}_{c}
Rec. center 1	1	1	1	1	1.5	2	2	2.5	3	1.5	2	2.5	0.5	1	1.5	1	1.5	2	2	2.5	3	1	1.5	2	1.5	2	2.5	2	2.5	3	0.16
Rec. center 2	0.5	0.67	1	1	1	1	1	1.5	2	1	1.5	2	2	2.5	3	0.5	1	1.5	1.5	2	2.5	1	1.5	2	1	1.5	2	0.5	1	1.5	0.13
Rec. center 3	0.33	0.4	0.5	0.5	0.67	1	1	1	1	0.5	1	1.5	1	1.5	2	0.5	1	1.5	1	1.5	2	0.5	1	1.5	0.5	1	1.5	2	2.5	3	0.10
Rec. center 4	0.4	0.5	0.67	0.5	0.67	1	0.67	1	2	1	1	1	2	2.5	3	1	1.5	2	2	2.5	3	1.5	2	2.5	0.5	1	1.5	2	2.5	3	0.13
Rec. center 5	0.67	1	2	0.33	0.4	0.5	0.5	0.67	1	0.33	0.4	0.5	1	1	1	1.5	2	2.5	2	2.5	3	1	1.5	2	2	2.5	3	1.5	2	2.5	0.12
Rec. center 6	0.5	0.67	1	0.67	1	2	0.67	1	2	0.5	0.67	1	0.4	0.5	0.67	1	1	1	1	1.5	2	0.5	1	1.5	0.5	1	1.5	1.5	2	2.5	0.09
Rec. center 7	0.33	0.4	0.5	0.4	0.5	0.67	0.5	0.67	1	0.33	0.4	0.5	0.33	0.4	0.5	0.5	0.67	1	1	1	1	1.5	2	2.5	1	1.5	2	0.5	1	1.5	0.06
Rec. center 8	0.5	0.67	1	0.5	0.67	1	0.67	1	2	0.4	0.5	0.67	0.5	0.67	1	0.67	1	2	0.4	0.5	0.67	1	1	1	0.5	1	1.5	1	1.5	2	0.07
Rec. center 9	0.4	0.5	0.67	0.5	0.67	1	0.67	1	2	0.67	1	2	0.33	0.4	0.5	0.67	1	2	0.5	0.67	1	0.67	1	2	1	1	1	2	2.5	3	0.09
Rec. center 10	0.33	0.4	0.5	0.67	1	2	0.33	0.4	0.5	0.33	0.4	0.5	0.4	0.5	0.67	0.4	0.5	0.67	0.67	1	2	0.5	0.67	1	0.33	0.4	0.5	1	1	1	0.04

Table B.16 Priority of each battery recovery center with respect to Sc7

Table B.17

Overall priority of each batter	y recovery center with res	spect to each sub-criterion

We4	Sc_1	Sc_2	Sc3	Sc4	Sc_5	Sc_6	Sc7
Recovery center 1	0.14	0.16	0.16	0.15	0.13	0.14	0.16
Recovery center 2	0.12	0.11	0.13	0.11	0.12	0.13	0.13
Recovery center 3	0.10	0.10	0.10	0.11	0.11	0.10	0.10
Recovery center 4	0.10	0.11	0.10	0.10	0.10	0.13	0.13
Recovery center 5	0.12	0.11	0.12	0.12	0.11	0.12	0.12
Recovery center 6	0.09	0.10	0.10	0.11	0.11	0.08	0.09
Recovery center 7	0.06	0.07	0.07	0.08	0.07	0.09	0.06
Recovery center 8	0.10	0.09	0.09	0.08	0.10	0.07	0.07
Recovery center 9	0.09	0.10	0.08	0.09	0.09	0.09	0.09
Recovery center 10	0.07	0.07	0.05	0.05	0.06	0.05	0.04

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